High Performance Computing: Tools and Applications

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Lecture 4

So far we have seen

#pragma omp parallel

#pragma omp for

```
#pragma omp parallel
 #pragma omp for
  for (i=0; i<n; i++)</pre>
  {
   a[i] = i;
  }
 // implied barrier
 // any thread sees all components of "a"
  // as updated
```

There is also an implied barrier at the end of sections and single constructs.

- With the private clause, private variables are undefined at the beginning of the loop, and values within the loop are not visible after the loop
- firstprivate clause instead initializes the private variables
- lastprivate clause copies value of last iteration to the variable after the loop

```
#include <stdio.h>
#include <omp.h>
int main (int argc, char *argv[])
  int i, a = 1000;
  #pragma omp parallel for firstprivate(a) lastprivate(a)
  for (i=0; i<10; i++)
   a = a + i;
  printf("value of a: %d\n", a);
```

#### return 0;

- Used when different threads must execute different code
- Must still create threads with parallel directive
- In general, p threads created and n sections

```
#pragma omp parallel
#pragma omp sections
{
    #pragma omp section
    printf("First thread %d\n", omp_get_thread_num());
    #pragma omp section
    printf("Second thread thread %d\n", omp_get_thread_num());
}
```

What happens if p < n? What happens if p > n?

- at most *n* threads run in parallel
- can also use firstprivate and lastprivate with obvious definitions of *first* and *last*
- can combine parallel and sections directives #pragma omp parallel sections like parallel for

```
#pragma omp parallel
{
    a = 255;
    #pragma omp for
    for (i=0; i<n; i++)
        b[i] = a;
}</pre>
```

- Depending on hardware, write to a may not be atomic, and thread 0 may read a when thread 1 has only partially written to it.
- Possible solution is to use a barrier after the write.
- Multiple threads writing to a is also unnecessary.
- Solution here is to use single directive.

- Used when code should only be executed by a single thread
- Can be executed by any thread (related master directive)

```
#pragma omp parallel
{
    #pragma single
    a = 255;
    #pragma omp for
    for (i=0; i<n; i++)
        b[i] = a;
}</pre>
```

Implied barrier at end of structured block (of single).

- thread-safe update of shared variables
- generally requires the compiler to use atomic instructions in the instruction set
- applies to single statements only (not blocks) with specific forms of updating a memory location

#pragma omp atomic
i = i + 1;

```
x = x binop expr;
```

where x is an I-value with scalar type, expr does not access the same storage as x, and binop is a binary operation, e.g., +.

For more details:

https://software.intel.com/en-us/node/524509

```
#pragma omp sections
```

```
#pragma omp single
```

#pragma omp master
// no implied barrier on exit

```
#pragma omp barrier
```

```
#pragma omp ordered
// used inside parallel for loop
```

#pragma omp critical [name]

```
#pragma omp atomic
// only for statements of specific form
```

- num\_threads sets the number of threads in parallel directive
- ► if controls the parallel directive depending on a condition
- nowait removes the barrier at the end of omp for and other constructs
- ordered needed to indicate that an ordered directive is within an omp for loop

#### Only spawn threads if the "problem" is large enough:

```
#pragma omp parallel if (n > 1000)
```

- Particles have radius a
- Cubical simulation box has width L and periodic boundaries
- Particles interact with each other
  - repulsive force when they overlap
  - other forces, e.g., when particles are charged

If distance *s* between particles *i* and *j* is less than 2a, then force on particle *i* due to particle *j* is

$$f_{ij} = k_r (2a - s) \cdot \hat{n}$$

where  $k_r = 100$  is the repulsion force constant and  $\hat{n}$  is the unit vector from *j* to *i*.

$$x(i) = x(i) + M \cdot f(i)\Delta t + \sqrt{2\Delta t} \cdot y(i)$$

where f(i) is the total force on particle *i* and M = 1 is a constant.

#### Code to compute forces from the positions

```
for (i=0; i<np; i++) {</pre>
    for (j=i+1; j<np; j++) {</pre>
        ri = \&pos[3*i];
        rj = \&pos[3*j];
        dx = remainder(ri[0]-rj[0], L);
        dy = remainder(ri[1]-rj[1], L);
        dz = remainder(ri[2]-rj[2], L);
        s2 = dx^*dx + dy^*dy + dz^*dz;
        if (s2 < 4.*a*a) {
            s = sqrt(s2);
             f = krepul*(2, -s);
             forces[3*i+0] += f*dx/s;
             forces[3*i+1] += f*dy/s;
             forces[3*i+2] += f*dz/s;
             forces[3*j+0] -= f*dx/s;
             forces[3*j+1] = f*dy/s;
            forces[3*j+2] -= f*dz/s;
```

Iterations on i are not independent, since different iterations can write to the same location in forces.

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- Each thread sums the forces locally, and then a sequential reduction computes the total force (requires storage local to each thread)
- Tabulate the overlaps in parallel, but sum the forces sequentially (could work if few overlaps; tabulation needs shared data structure)

- Update your code from Exercise 2 to include repulsive interactions between particles when they overlap. Parallelize using OpenMP and run on jinx or deepthought.
- Compare the performance between using critical sections, atomic operations, and independent iterations (which do twice the number of distance computations).
- Submit your results in the ex04 directory (do not forget to update your fork), including
  - ex04.c or ex04.cpp source file and makefile
  - ex04.pdf report with performance comparison
- Due 10 pm, Monday, Sept. 5