High Performance Computing: Tools and Applications

Edmond Chow School of Computational Science and Engineering Georgia Institute of Technology

Lecture 5

Brownian dynamics with periodic boundary conditions

Simulate an *infinite* system of particles using a periodic simulation box with a fixed number of particles



Brownian dynamics with periodic boundary conditions

- When a particle exits the box, an *image* of the particle enters the box
- We only need to keep track of one of these two particles
 - keep track of the original particle that left the box
 - since we need to measure how far it has moved
 - do not need to "wrap" that particle's positions back into the box
- However, when computing distances to see if particles overlap, we need to consider all possible images of all particles
 - when computing the distance between a particle and another particle and all its images, convert that distance to the smallest distance
 - this is handled by:

```
dx = remainder(ri[0]-rj[0], L);
dy = remainder(ri[1]-rj[1], L);
dz = remainder(ri[2]-rj[2], L);
```

Mean squared displacement (MSD)

In 3D, the mean square displacement of particles is

 $\langle r^2 \rangle = 6Dt$

where t is the time interval during which particles are moving, and D is the diffusion constant.

"Displacement" is used to mean the *magnitude* of the displacement; not the cumulative distance moved (which is linear in *t*)

Therefore the diffusion constant can be computed as follows:

- Consider the graph of the mean of the square of the displacement for each t (note, this is different from the square root of the average displacement)
- This graph is expected to be linear in t (except for very small t in some cases)
- The slope of this line divided by 6 is D

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 - ► Suppose that particles have radius *a* = 1
 - Suppose that we want a volume fraction of particles of φ = 0.1 (when particles are not overlapping) for *n* particles
 - Solve for *L* in $\frac{4}{3}\pi a^3 n = \phi L^3$

Different volume fractions will lead to different diffusion constants D

- No need to make pull requests
- Executables and objects are normally not checked into the repository
- Do not use tabs in your source files
 - My editor generally doesn't map tabs to the same number of spaces as your editor; therefore we don't see your source the way you intended
 - Use your editor settings to change tabs to spaces

- In HPC research, use of good algorithms is just as important as good parallel implementations
- Usually, the best sequential algorithms are not the best parallel algorithms, and the best parallel algorithms can be very complicated

- ► For *n* particles, there are n(n+1)/2 possible interactions
- How to reduce the complexity to O(n) ?

Cell lists

- ► Divide space into a set of cells, with cell width ≥ r_c, where r_c = 2 in our case
- Particle *i* interacts only with particles in its own cell and its neighboring cells
- One sweep through all the particles is used to construct the *cell list* data structure (list of particles in each cell)
- When particles move, the cell list data structure must be reconstructed



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Interesting optimization for cell lists

- Make the cells slightly larger, so that they can be reused for many time steps (or use cells that are one layer beyond the immediate neighbor cells)
- How can we optimize to exploit Newton's third law, i.e., don't compute equal and opposite interactions?
- Traversing all the particles to construct the cell lists can be expensive

Neighbor list method

- Exploits the idea that particles are moving slowly
- Each particle maintains a list of neighbors within a cutoff of r_v > r_c
- The neighbor list can be reused for a given number of time steps, in which it could be guaranteed that an particle beyond r_v does not move closer than r_c
- How to exploit Newton's third law?



How do we construct the neighbor list?

- ► Naive: O(n²)
- Better: use cell lists whenever the neighbor lists must be reconstructed
 - this is the strategy of many particle codes

Code will be in the repo ${\tt ex05}$ directory.

- Integrate the (sequential) interactions function into your Brownian dynamics code; you are free to make any modifications
- Compare the performance between your Exercise 4 code and your code using the interactions function
- ► Submit your results in the ex05 directory, including
 - ex05.c or ex05.cpp source file and makefile
 - ex05.pdf report with performance comparison
- Due 10 pm, Wed., Sept. 7
- We are working toward a parallel version of the interactions function for mini-project 1.