High Performance Computing: Tools and Applications

Edmond Chow School of Computational Science and Engineering Georgia Institute of Technology

Lecture 7

gotham.cc.gatech.edu (mic0 to mic7)

joker.cc.gatech.edu (mic0 to mic4)

- Each server has separate accounts and home directories (please restrict yourself to 5 GB in your home directory)
- Each server has 8 Intel Xeon Phi coprocessors
- Each coprocessor has 60 cores
- Each core has 4 hardware threads

Change your password on the host using passwd

Logins onto the coprocessors use ssh (already set up for you)

- Three ways to run on Xeon Phi
 - native mode (coprocessor runs Linux uOS)
 - offload: program executes on host and offloads work to coprocessors
 - symmetric: MPI is used between hosts and coprocessors
- We will primarily use native mode (copy your executable onto the coprocessor and run it on the coprocessor)
- When you log into these machines, treat the host as a head node, where you can cross-compile for the coprocessors

- 8 GB local memory on the coprocessor card
- Do not have any permanent user file systems
- All created file systems reside in RAM (except network file systems) and thus have limited space
- Coprocessors have separate home directories (assuming native mode)
- Do not store anything of value on the coprocessors (they will disappear if the coprocessors are rebooted)
- In fact, only treat this space as scratch space. Only copy over executables, and immediately copy back output files. (Treat as if you are using the coprocessors as batch processors.)

- gotham and joker have the latest Intel compilers and tools
- Intel compilers often get better performance than Gnu compilers on Intel processors
- ► We also need Intel compilers for compiling for Intel Xeon Phi
- We will primarily use Intel Xeon Phi and Intel compilers in the rest of the course

To set up environment variables for Intel compilers on host (for architecture intel64):

source /opt/intel/compilers_and_libraries/\
linux/bin/compilervars.sh intel64

The C compiler is icc and the C++ compiler is icpc

gotham:~\$ which icc /opt/intel/compilers_and_libraries_2016.2.181/linux/bin/intel64/icc Note some different compiler options

icc -02 -qopenmp ...

More information:

```
https://software.intel.com/en-us/
intel-cplusplus-compiler-16.0-user-and-reference-guide
```

- By default, threads can be assigned to any core, and may hop between cores. This helps balance the load on the cores, but usually you do not want this in HPC.
- Bind threads to specific cores. Advantages:
 - thread local information in the core's cache can be reused
 - thread stays on a socket, and has better access to memory associated with that socket (NUMA issues)
 - some cores share cache with some other cores; place threads that share memory on *nearby* cores

Thread affinity (gnu compilers)

- ► Controlled by GOMP_CPU_AFFINITY environment variable
- Bind thread 0 to core 7, thread 1 to core 6. Any additional threads are assigned starting with the beginning of the list.
 GOMP_CPU_AFFINITY=7, 6
- Bind all threads to core 0 GOMP_CPU_AFFINITY=0
- Bind first 4 threads to cores 0-3, etc. GOMP_CPU_AFFINITY=0-3
- ► Bind first 4 threads to cores 0, 2, 4, 6 GOMP_CPU_AFFINITY=0-7:2
- ► core may mean logical core if hyperthreading is used

- Controlled by KMP_AFFINITY environment variable, and is more flexible than the Gnu version
- Two main modes: compact and scatter

```
KMP_AFFINITY=compact
KMP_AFFINITY=scatter
```

compact and scatter

- 2 sockets, 4 cores/socket
- Number is thread id

compact





Might not use all sockets

scatter



compact can be a bad option if you might be using fewer threads than cores on a node.

granularity=core

- The affinity mode can be modified by adding a granularity option which can be useful if hyperthreading is used
- default granularity is core
- 2 sockets, 4 cores/socket, 2-way hyperthreading

granularity=core,compact



granularity=core,scatter

0,8	2,10	4,12	6,14	1,9	3,11	5,13	7,15

Thread can only float between hardware contexts on a core

2 sockets, 4 cores/socket, 2-way hyperthreading

granularity=fine,compact





granularity=fine,scatter





Usually no need to bind threads to hardware thread contexts

balanced mode (Intel Xeon Phi only)

On Intel Xeon Phi coprocessors, balanced mode is available

Example for 8 threads



4 cores and 4 HW threads per core. Note: "balanced" is only for Intel Xeon Phi.

- bind to any hardware thread on core (default) granularity=core, balanced
- bind to single hardware thread granularity=fine, balanced

- another mode: none
- another modifier: verbose

Print affinity information, set mode to none
KMP_AFFINITY="verbose, none"

- For bandwidth-bound codes, the optimum number of threads is often less than the number of cores. Distribute and choose the number of threads to reduce contention and fully utilize the memory controllers (use scatter).
- For compute-bound codes, use hyperthreading and all available hyperthreads. Threads operating on adjacent data should be placed on the same core (or nearby) in order to share cache (use compact).
- On Intel Xeon Phi, balanced often works best. (Should we have this option on CPUs?)

- Write a shared memory parallel code for Brownian dynamics simulation with steric interactions
- Main effort will be to parallelize the interactions function and to compute the repulsive forces in parallel
- Run on single Intel Xeon Phi coprocessor
- Speed will be a major factor of your evaluation; you can use any Intel/gcc compiler feature to make your code faster and you can even write assembly if you want!
- Due in proj1 directory at 10 pm, Sat., Sept. 24

Mini-Project 1: Grading

- 0-6 points for parallel implementation producing correct results
 - correctness will be checked by computing diffusion coefficient of a simulation
 - points will be deducted for bad coding style, e.g., spaghetti code, insufficient comments, irregular indentation
- 0-6 points for speed
 - use the test harness code (checked into proj1) and provide a script (called from the makefile) for us to run (including copying files to the coprocessor, setting any environment variables for affinity, number of threads, etc.)
 - 6 points for fastest submission and 0 points for slowest submission
 - 0 points for incorrect code
- 0-3 points for report (projl.pdf)
 - graph of time per timestep for 10000 particles at 20 percent volume fraction (use logarithmic y-axis) vs. number of threads
 - describe your final parallelization and why you consider your parallelization to be faster than other choices

- harness.c is the main program (you can make minimal changes if necessary)
- most of your changes should go in bd.c or other files
- Update the makefile as needed
- Note: the test harness outputs a *trajectory* in xyz file format. This trajectory can be used for data analysis and making movies.

xyz format

- This is a single plain text file, with each *frame* concatenated one after the other.
- Each frame has the following format:
 - First line is the number of particles
 - Second line is a comment. But we use it to specify the simulated time since the start of the simulation, and the box width L
 - Each subsequent line gives the particle type and the particle position (you can ignore the particle type for now)

Example:

```
344
227.000000 20.180992
0 24.685087 -12.790052 3.772569
0 -26.050274 10.934415 -32.012157
0 -5.682880 -19.800725 9.765145
```

Making a movie of your simulation (useful for debugging)

- Download and install VMD (visual molecular dynamics) http://www.ks.uiuc.edu/Research/vmd/ on your local computer (Windows, OSX, Linux)
- run using vmd output.xyz
- at the VMD prompt, use this command to set the visualization style:

```
mol modstyle 0 0 {vdw 1 20}
```

to see a simulation using periodic boundary conditions:

```
pbc set {20.181 20.181 20.181} -all
pbc wrap -all
pbc box -center unitcell -color tan
```

```
where 20.181 is the box width
```

use the *play* button to start the movie

Use the matlab script a_msd3.m. At the matlab prompt:

out = a_msd3('output.xyz');