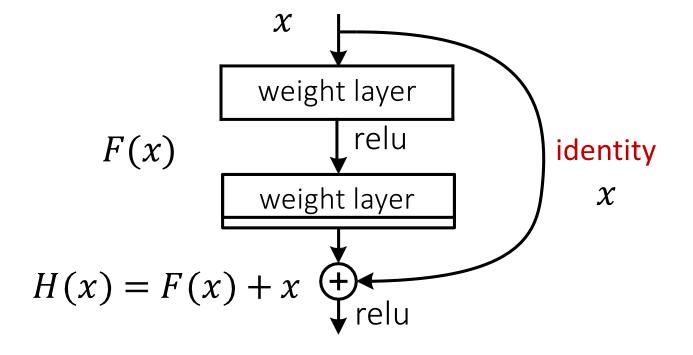
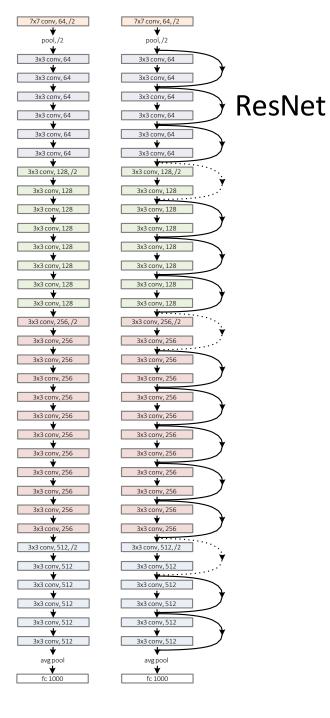
Recap: Resnet

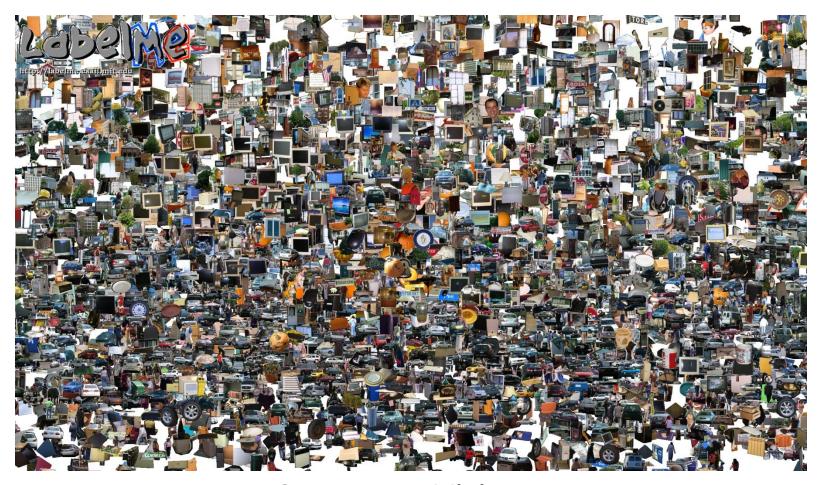
plain net

• F(x) is a residual mapping w.r.t. identity





Opportunities of Scale



Computer Vision
James Hays

Outline

Opportunities of Scale: Data-driven methods

- The Unreasonable Effectiveness of Data
- Scene Completion
- Im2gps
- Recognition via Tiny Images

Computer Vision Class so far

- The geometry of image formation
 - Ancient / Renaissance
- Signal processing / Convolution
 - 1800, but really the 50's and 60's
- Hand-designed Features for recognition, either instance-level or categorical
 - 1999 (SIFT), 2003 (Video Google), 2005 (Dalal-Triggs), 2006 (spatial pyramid bag of words)
- Learning from Data
 - 1991 (EigenFaces) but late 90's to now especially

What has changed in the last 15 years?

- The Internet
- Crowdsourcing
- Learning representations from the data these sources provide (deep learning)

Google and massive data-driven algorithms

A.I. for the postmodern world:

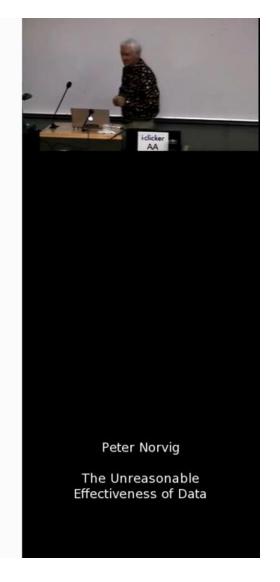
- all questions have already been answered...many times, in many ways
- Google is dumb, the "intelligence" is in the data

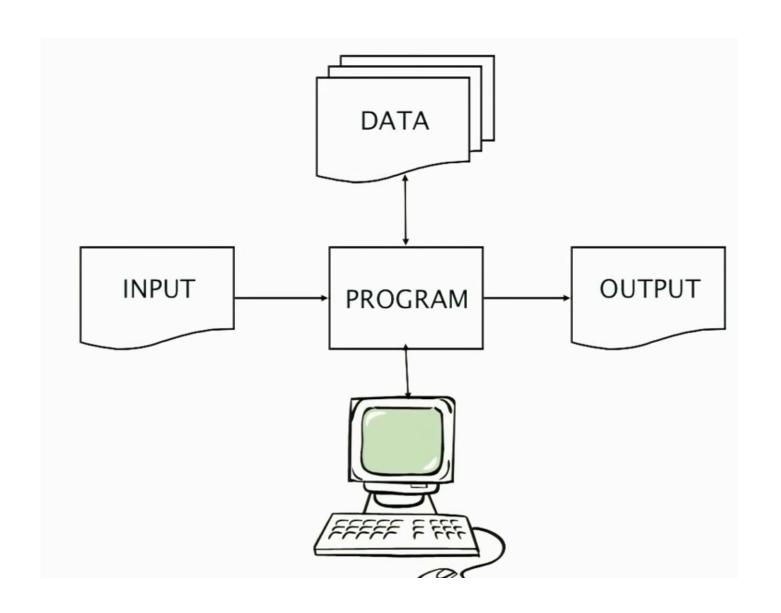


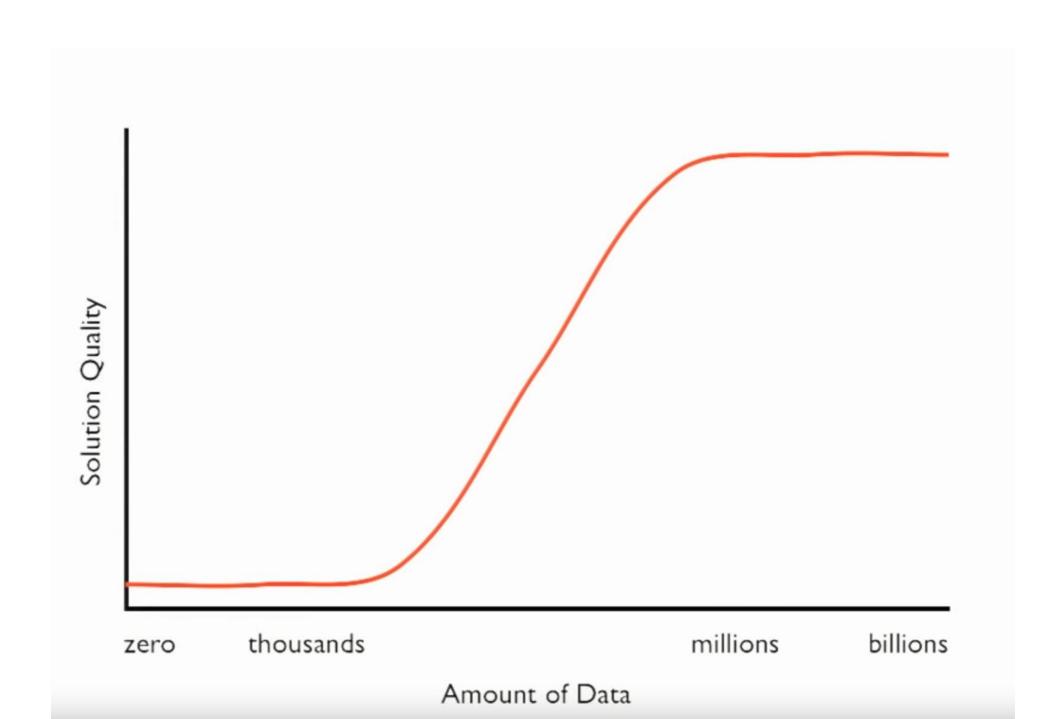
The Unreasonable Effectiveness of Data

Peter Norvig Google



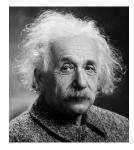






The onable Effectiveness of Math

• "The miracle of the appropriateness of the language of mathematics..." **Eugene Wigner**





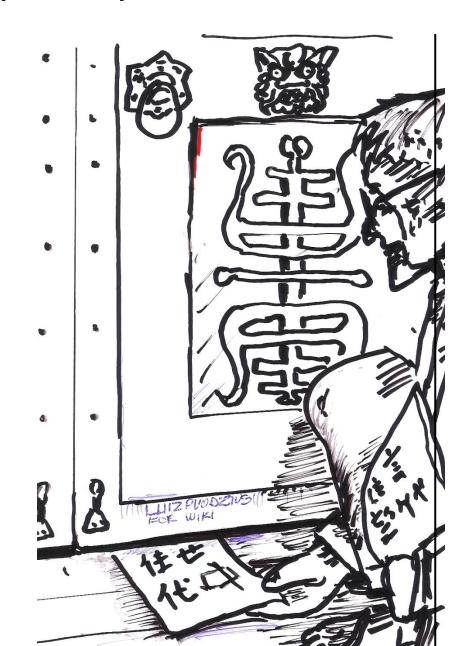


- "The most incomprehensible thing about the universe is that it is comprehensible." **Albert Einstein**
- "There is only one thing which is more unreasonable than the unreasonable effectiveness of mathematics in physics, and this is the unreasonable ineffectiveness of mathematics in biology." Israel Gelfand
- "We should stop acting as if our goal is to author extremely elegant theories, and instead embrace complexity and make use of the best ally we have: the unreasonable effectiveness of data." Peter Norvig

Chinese Room, John Searle (1980)

If a machine can convincingly simulate an intelligent conversation, does it necessarily understand? In the experiment, Searle imagines himself in a room, acting as a computer by manually executing a program that convincingly simulates the behavior of a native Chinese speaker.

Most of the discussion consists of attempts to refute it. "The overwhelming majority," notes *BBS* editor Stevan Harnad, "still think that the Chinese Room Argument is dead wrong." The sheer volume of the literature that has grown up around it inspired Pat Hayes to quip that the field of cognitive science ought to be redefined as "the ongoing research program of showing Searle's Chinese Room Argument to be false.





Questions from the piece:

Q1. Does the Chinese Room argument prove the impossibility of machine consciousness?

A1: Hell no. ... See More



Can Machines Become Moral?

The question is heard more and more often, both from those who think that machines cannot become moral, and who think that to believe otherwise is a dangerous illusion, and from those who think that machines must become moral,...

BIGQUESTIONSONLINE.COM | BY DON HOWARD



30 Comments 20 Shares





Big Idea

- Do we need computer vision systems to have strong AI-like reasoning about our world?
- What if invariance / generalization isn't actually the core difficulty of computer vision?
- What if we can perform high level reasoning with brute-force, data-driven algorithms?

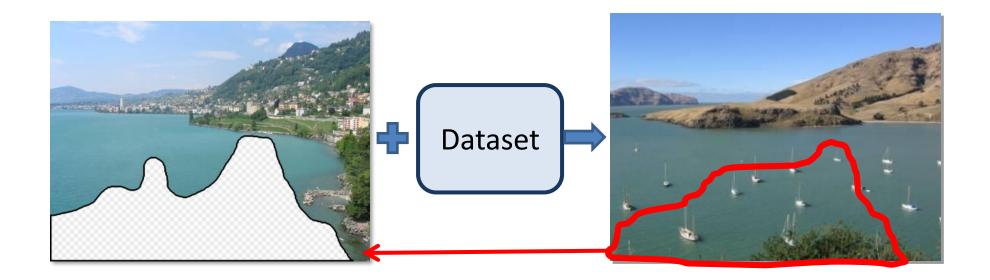
Scene Completion

[Hays and Efros. Scene Completion Using Millions of Photographs. SIGGRAPH 2007 and CACM October 2008.]

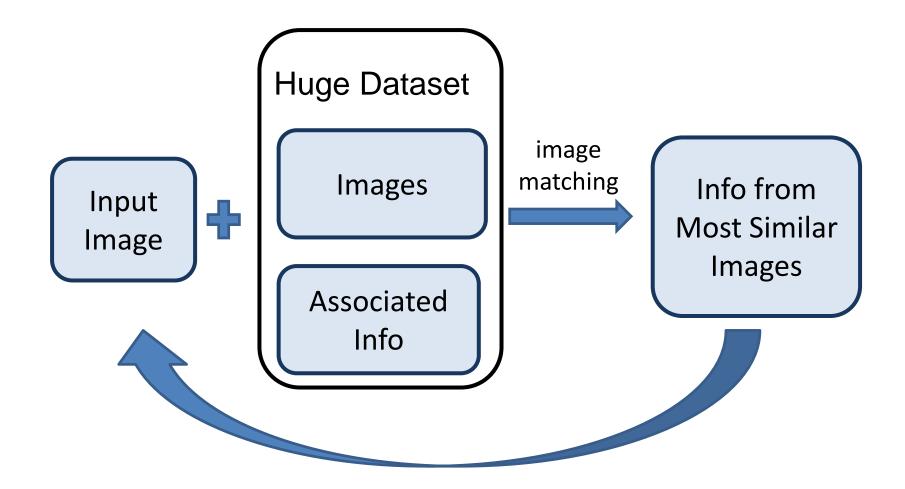
http://graphics.cs.cmu.edu/projects/scene-completion/

How it works

- Find a similar image from a large dataset
- Blend a region from that image into the hole



General Principal



Hopefully, If you have enough images, the dataset will contain very similar images that you can find with simple matching methods.

How many images is enough?

























Nearest neighbors from a collection of 20 thousand images



Nearest neighbors from a collection of 2 million images

Image Data on the Internet

- Flickr (as of Sept. 19th, 2010)
 - 5 billion photographs
 - 100+ million geotagged images
- Facebook (as of 2009)
 - 15 billion

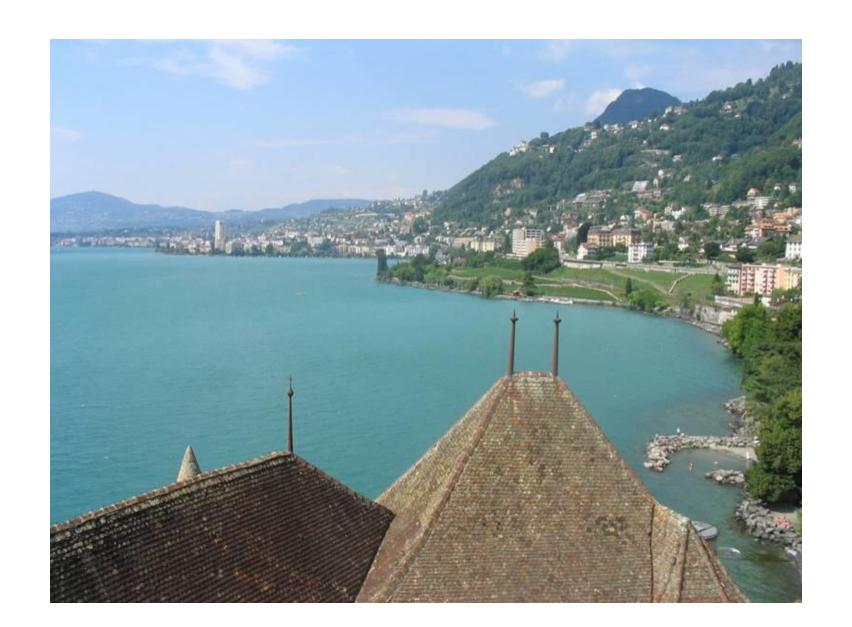
Image Data on the Internet

- Flickr (as of Nov 2013)
 - 10 billion photographs
 - 100+ million geotagged images
 - 3.5 million a day
- Facebook (as of Sept 2013)
 - 250 billion+
 - 300 million a day
- Instagram
 - 55 million a day

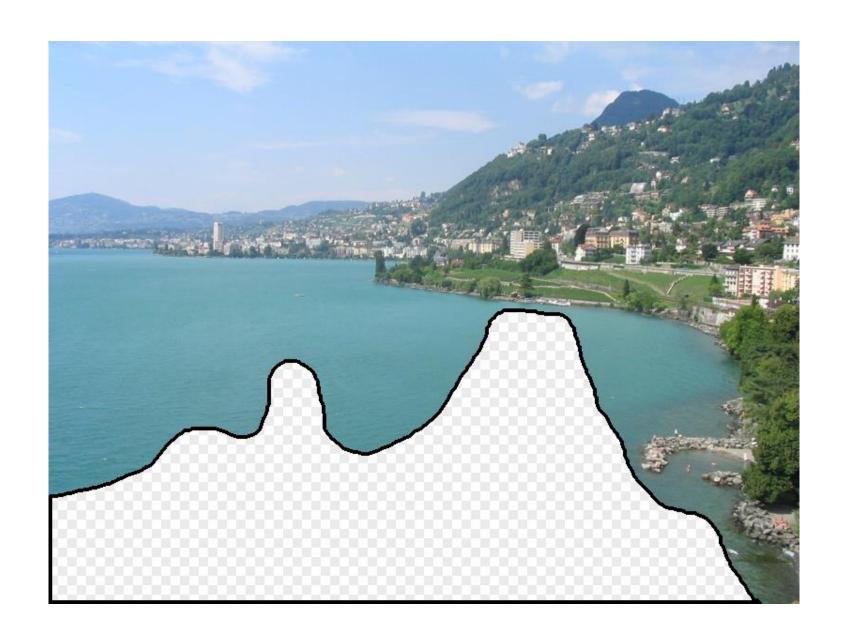
Scene Completion: how it works

[Hays and Efros. Scene Completion Using Millions of Photographs. SIGGRAPH 2007 and CACM October 2008.]

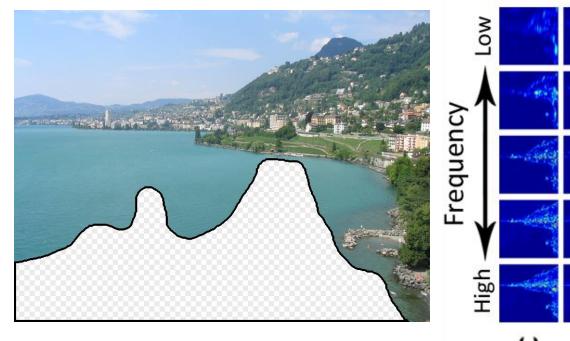
The Algorithm

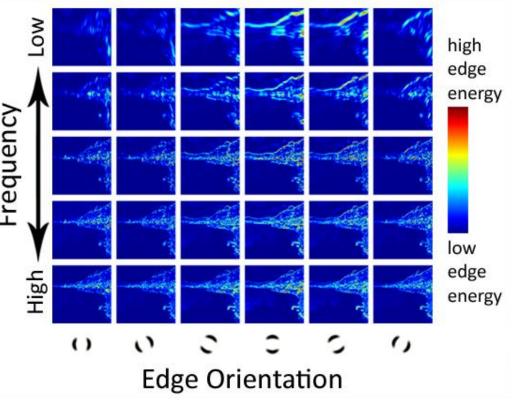


Scene Matching

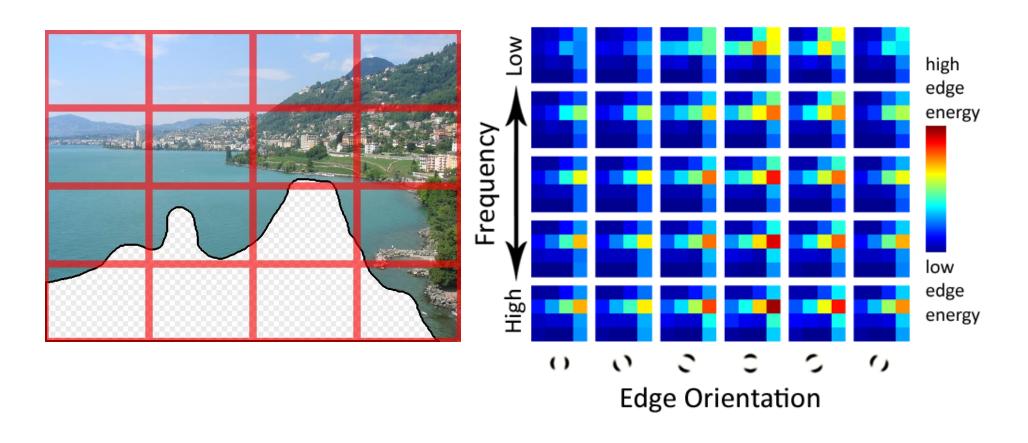


Scene Descriptor



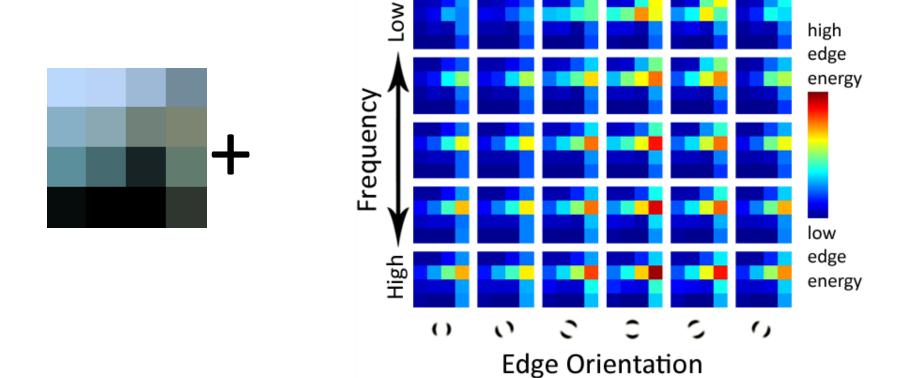


Scene Descriptor

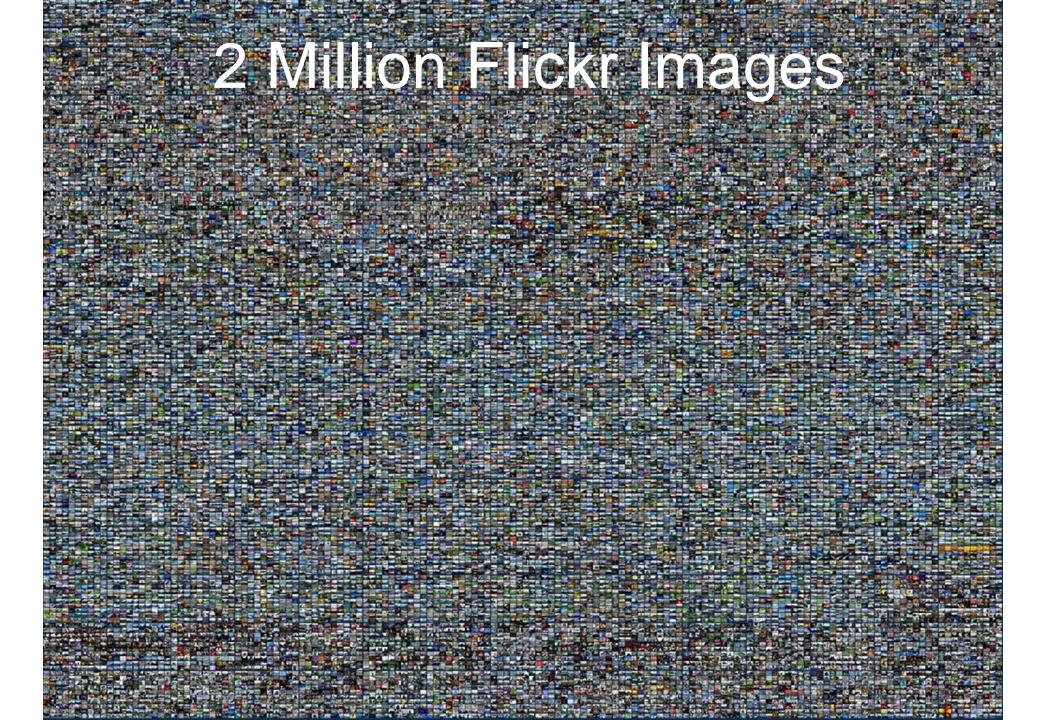


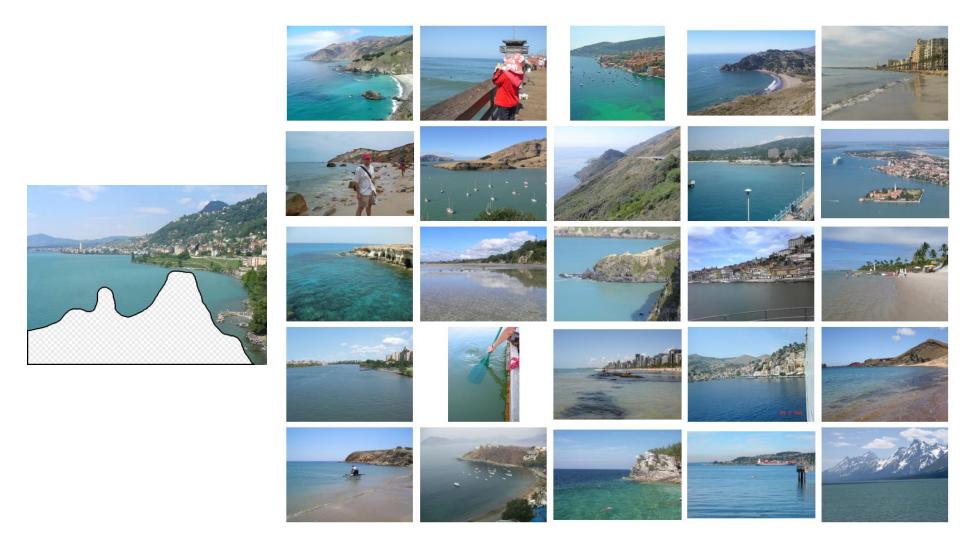
Scene Gist Descriptor (Oliva and Torralba 2001)

Scene Descriptor



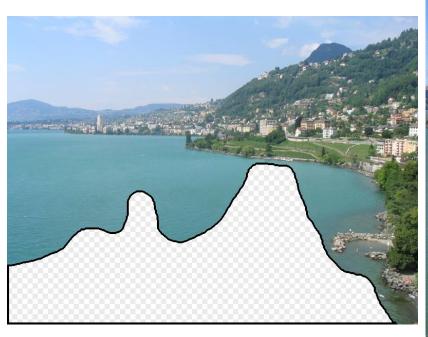
Scene Gist Descriptor (Oliva and Torralba 2001)





... 200 total

Context Matching

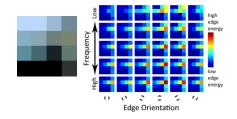






Result Ranking

We assign each of the 200 results a score which is the sum of:



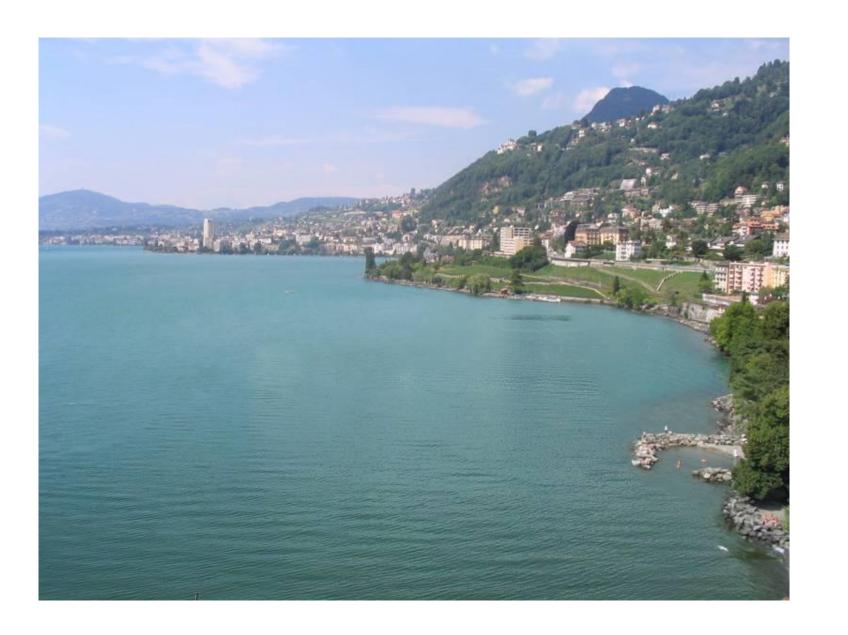
The scene matching distance



The context matching distance (color + texture)



The graph cut cost





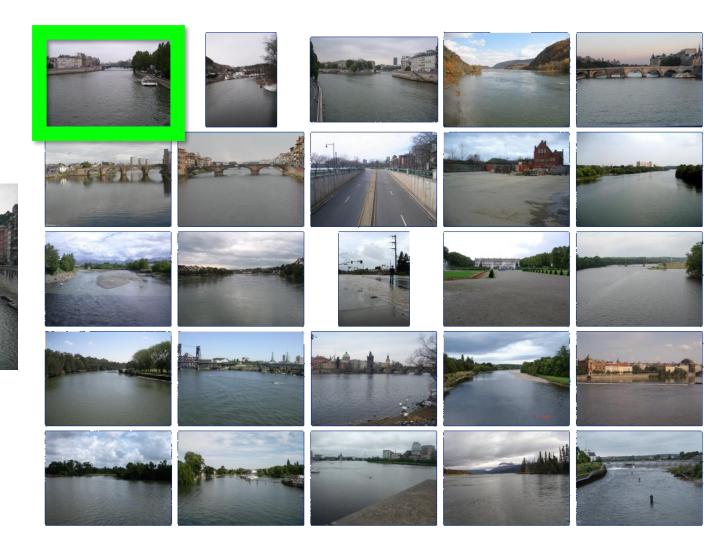










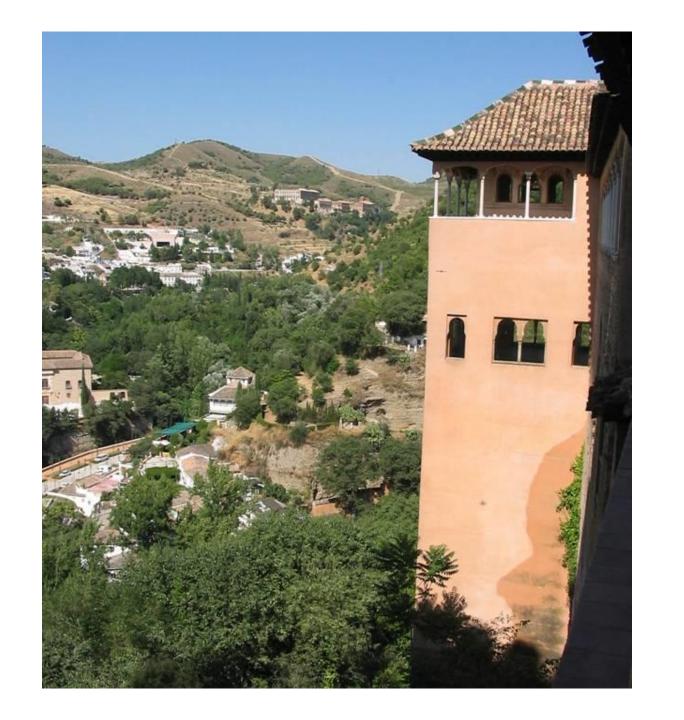


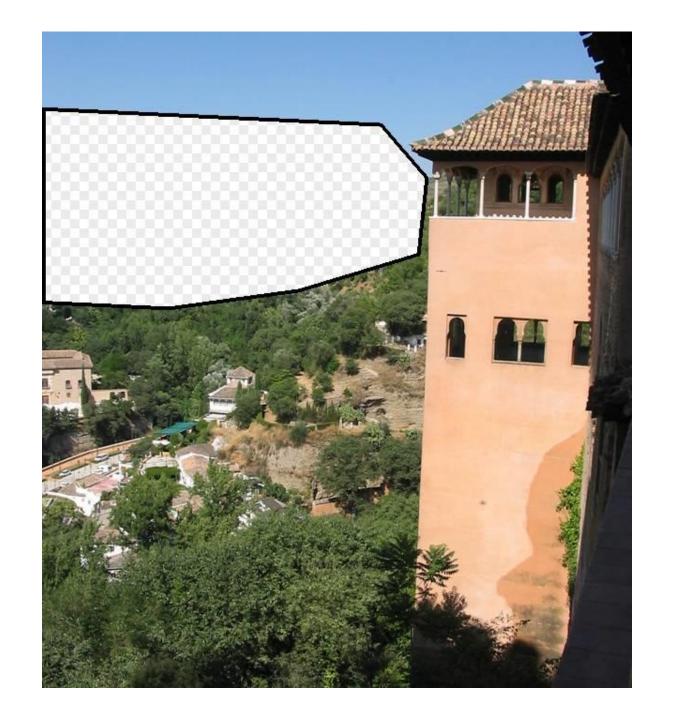
... 200 scene matches

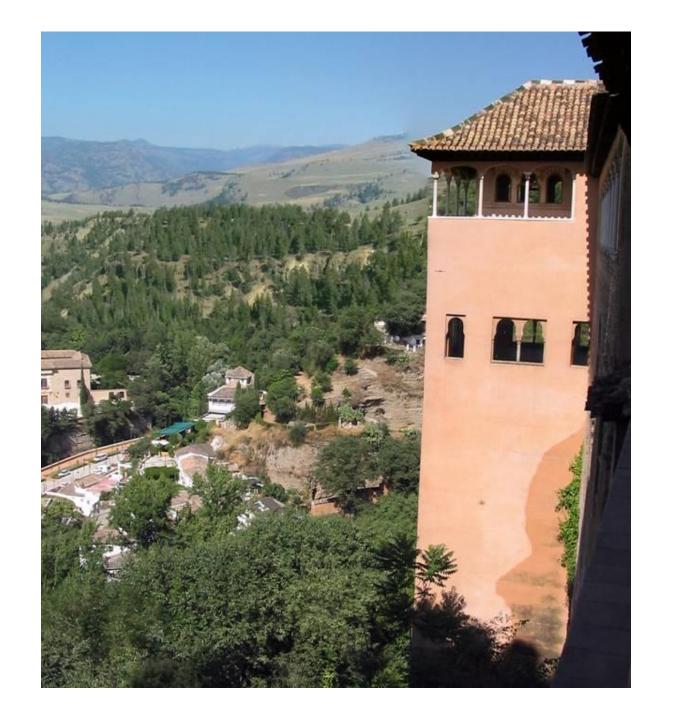












Which is the original?





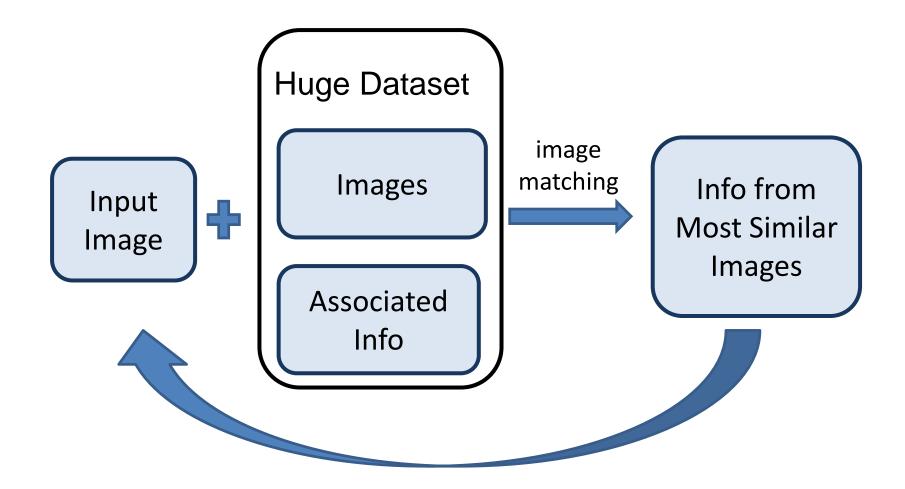


Outline

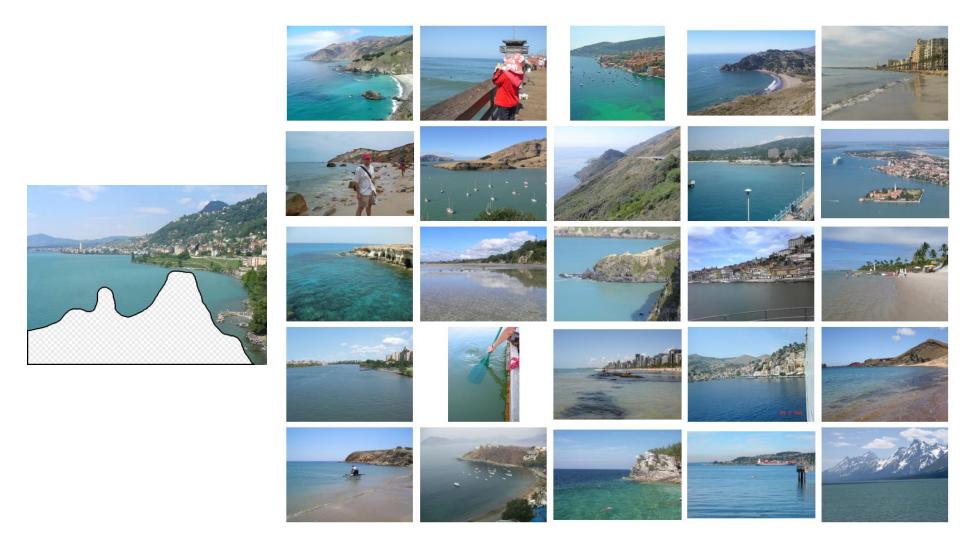
Opportunities of Scale: Data-driven methods

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- Recognition via Tiny Images

General Principal

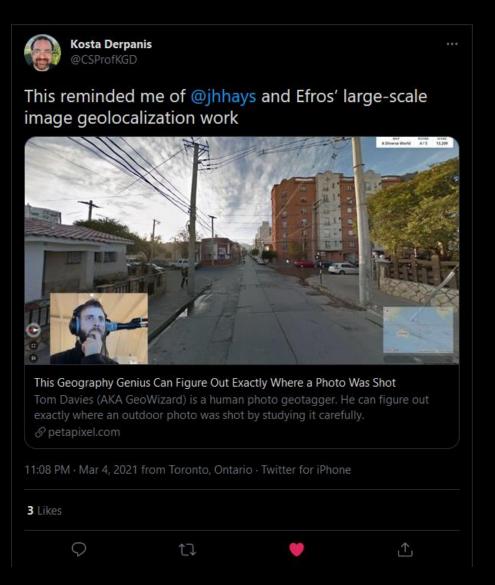


Hopefully, If you have enough images, the dataset will contain very similar images that you can find with simple matching methods.



... 200 total

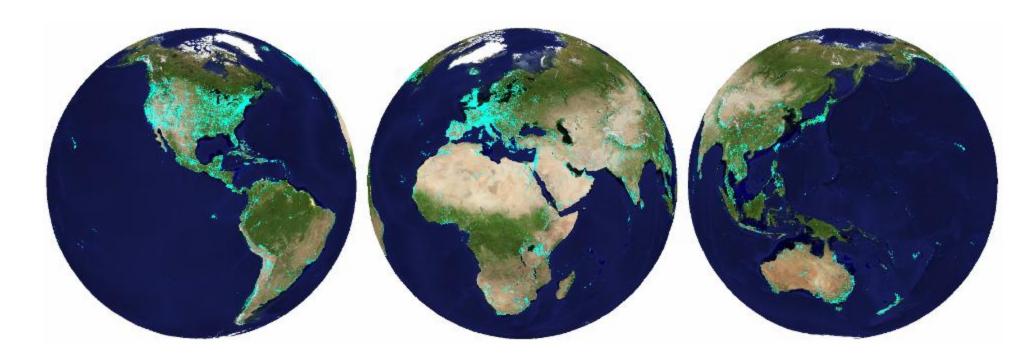




https://www.geoguessr.com/

https://www.youtube.com/c/GeoWizard/videos

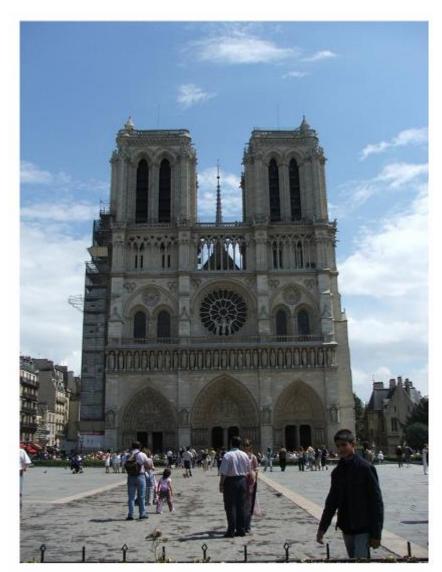
im2gps (Hays & Efros, CVPR 2008)

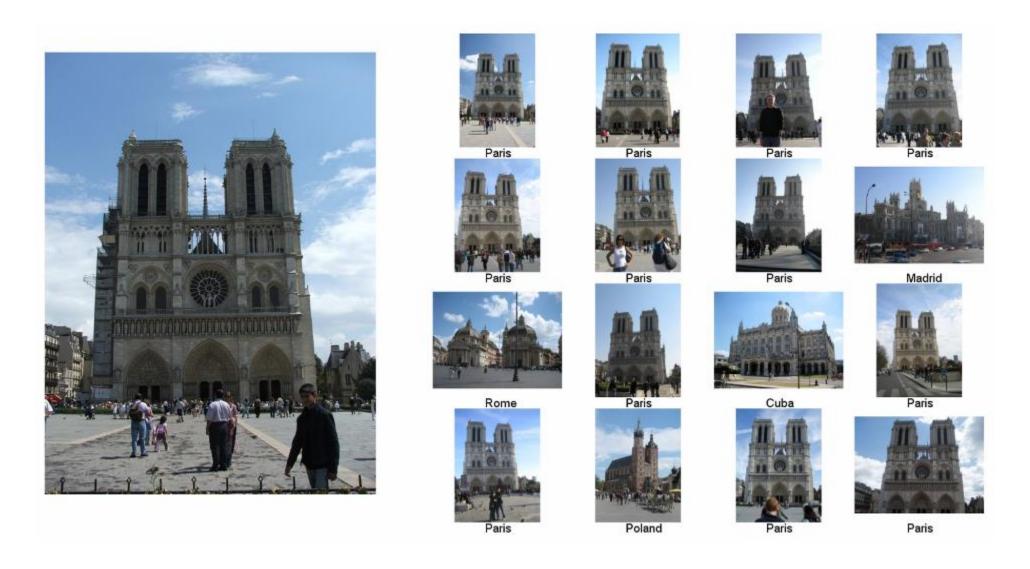


6 million geo-tagged Flickr images

http://graphics.cs.cmu.edu/projects/im2gps/

How much can an image tell about its geographic location?





Nearest Neighbors according to gist + bag of SIFT + color histogram + a few others





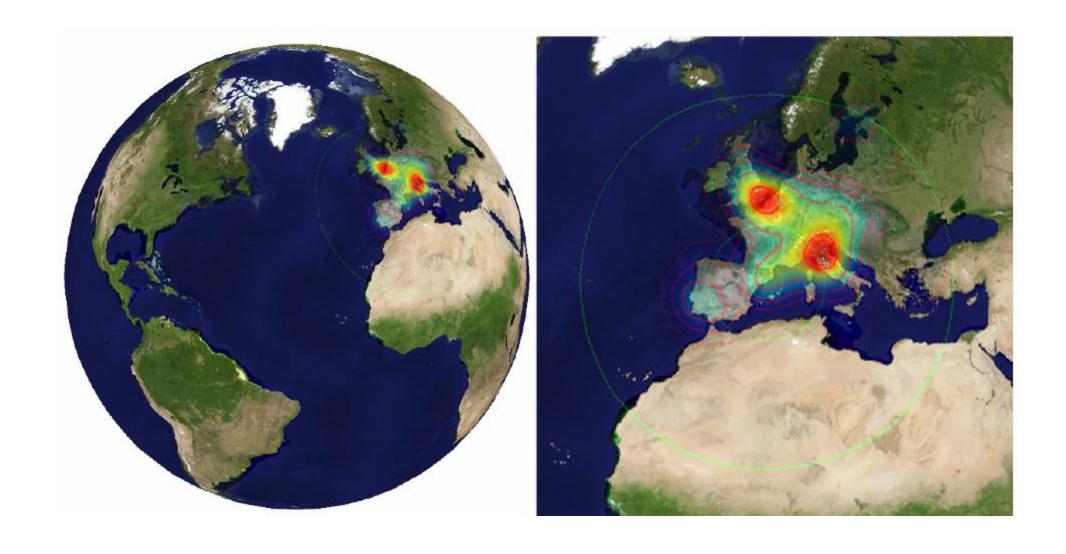
Im2gps



Example Scene Matches



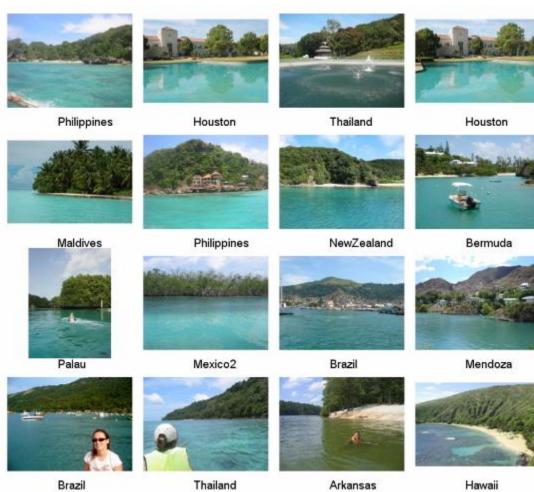
Voting Scheme

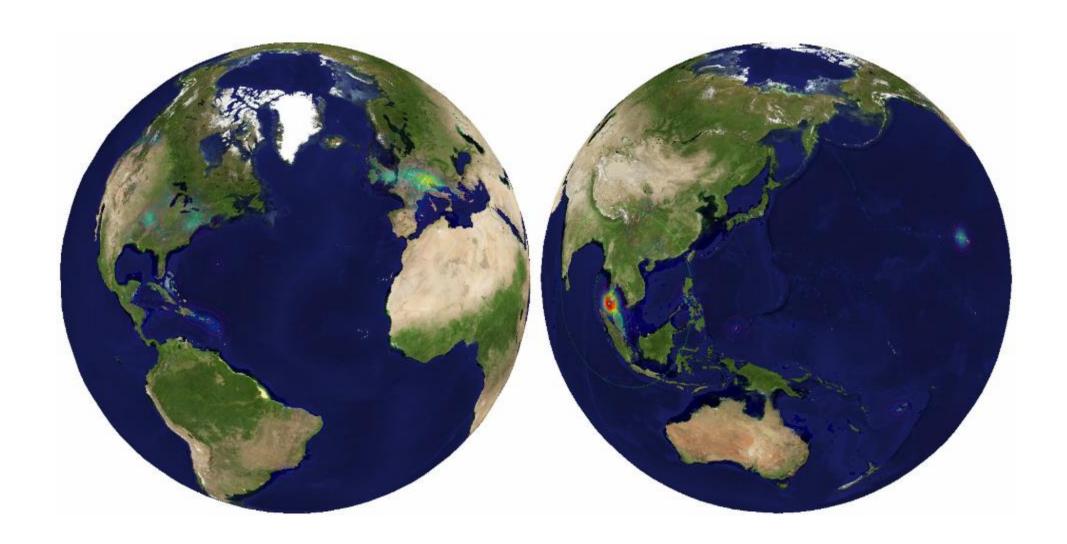


im2gps

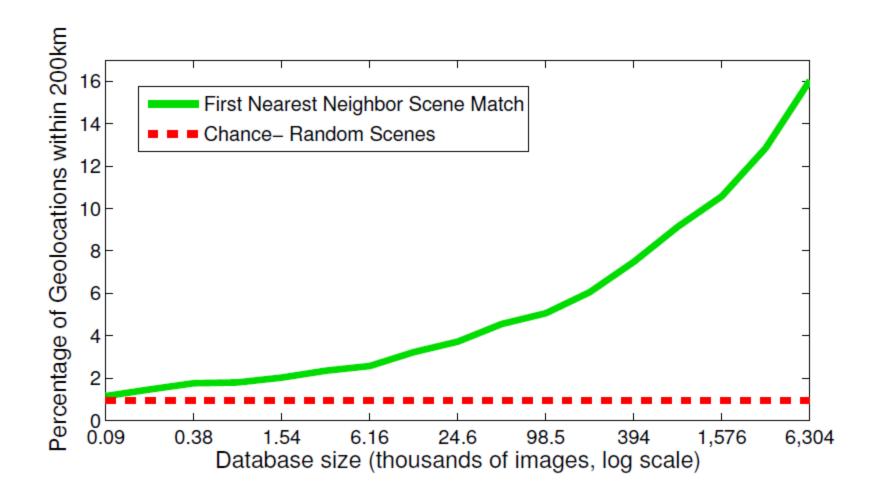






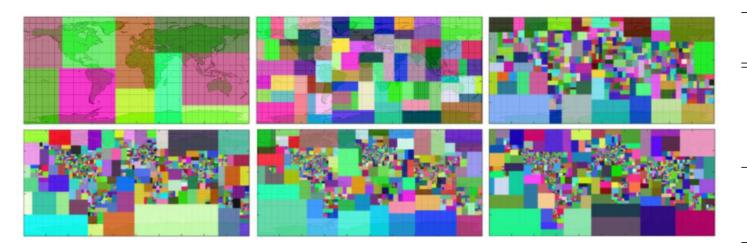


Effect of Dataset Size



Follow up works

- PlaNet photo geolocation with convolutional neural networks. T.
 Weyand, I. Kostrikov, and J. Philbin. ECCV 2016
- Revisiting IM2GPS in the Deep Learning Era.
 Nam Vo, Nathan Jacobs, James Hays. ICCV 2017



	Street	City	Region	Country	Cont.
Threshold (km)	1	25	200	750	2500
Human*			3.8	13.9	39.3
Im2GPS [9]		12.0	15.0	23.0	47.0
Im2GPS [10]	02.5	21.9	32.1	35.4	51.9
PlaNet [36]	08.4	24.5	37.6	53.6	71.3
[L] 7011C	06.8	21.9	34.6	49.4	63.7
[L] kNN, σ =4	12.2	33.3	44.3	57.4	71.3
28m database	14.4	33.3	47.7	61.6	73.4

Tiny Images



80 million tiny images: a large dataset for non-parametric object and scene recognition Antonio Torralba, Rob Fergus and William T. Freeman. PAMI 2008.

http://groups.csail.mit.edu/vision/TinyImages/

256x256











dining room

dining room

waiting area

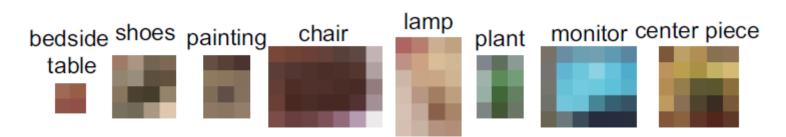
office



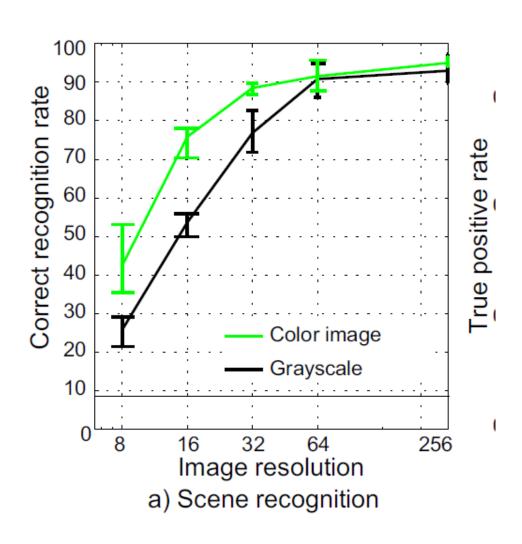
c) Segmentation of 32x32 images



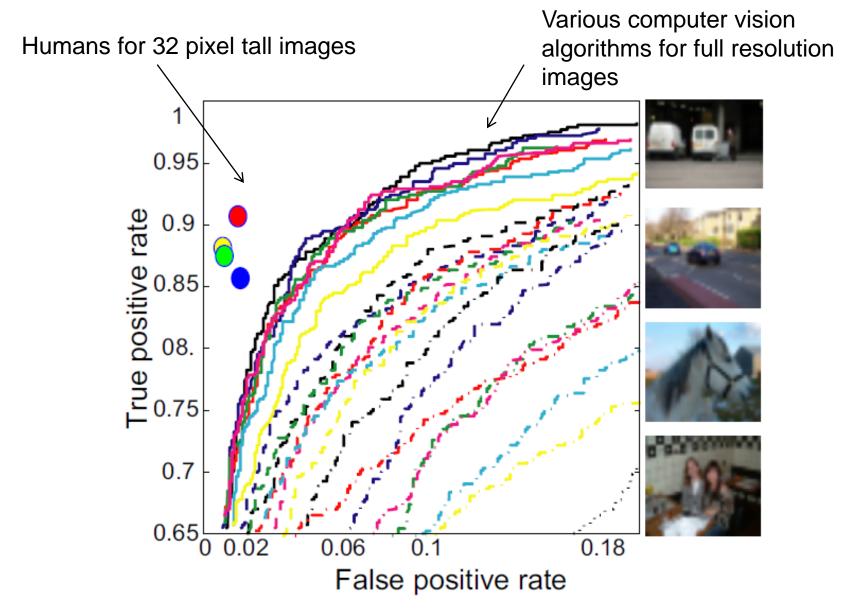
c) Segmentation of 32x32 images



Human Scene Recognition



Humans vs. Computers: Car-Image Classification



Powers of 10

Number of images on my hard drive:

 10^{4}

10⁸

Number of images seen during my first 10 years:

(3 images/second * 60 * 60 * 16 * 365 * 10 = 630720000)



Number of images seen by all humanity:

106,456,367,669 humans¹ * 60 years * 3 images/second * 60 * 60 * 16 * 365 = 1 from http://www.prb.org/Articles/2002/HowManyPeopleHaveEverLivedonEarth.aspx

10²⁰

Number of photons in the universe:

10⁸⁸

Number of all 32x32 images:

256 32*32*3 ~ 10⁷³⁷³

10⁷³⁷³

Scenes are unique



But not all scenes are so original











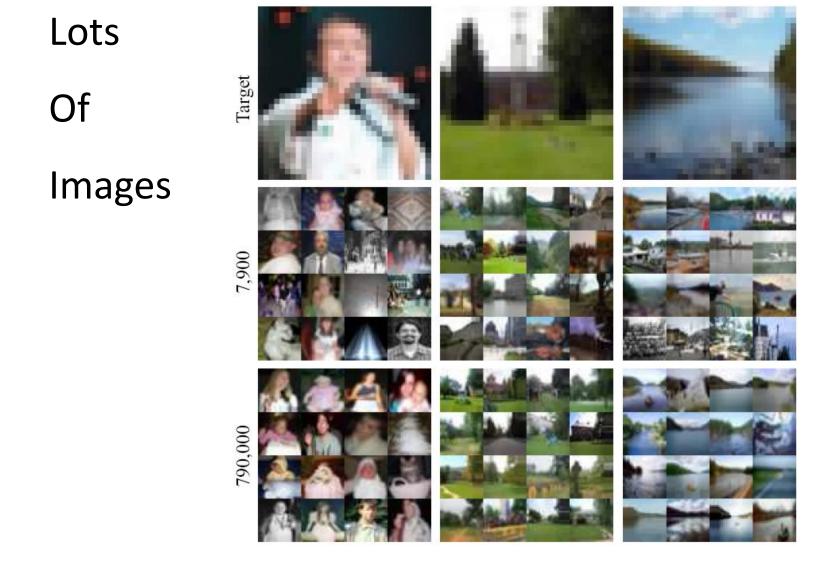












Lots Target Of Images 7,900 790,000 79,000,000

Application: Automatic Colorization



Input



Color Transfer



Color Transfer



Matches (gray)



Matches (w/ color)



Avg Color of Match

Application: Automatic Colorization



Input



Matches (gray)



Color Transfer



Matches (w/ color)

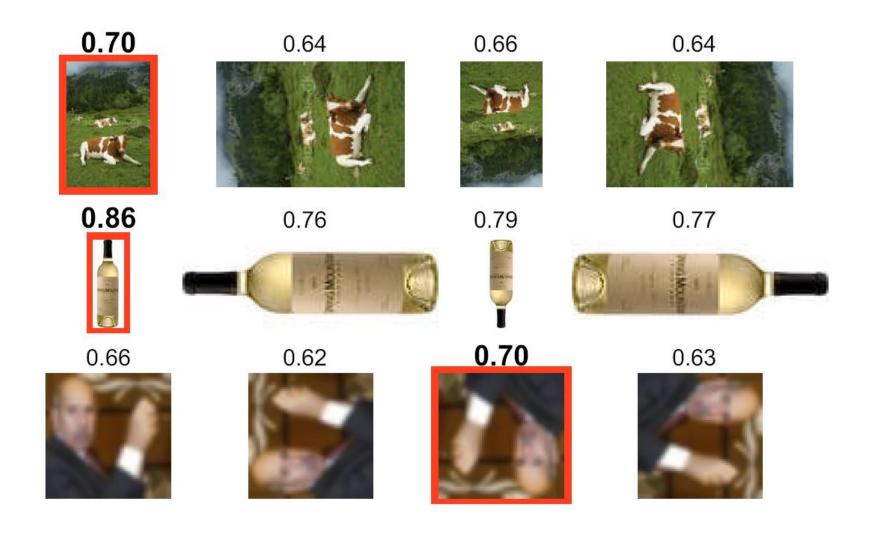


Color Transfer



Avg Color of Match

Automatic Orientation Examples



Summary

- With billions of images on the web, it's often possible to find a close nearest neighbor
- In such cases, we can shortcut hard problems by "looking up" the answer, stealing the labels from our nearest neighbor. For example, simple (or learned) associations can be used to synthesize background regions, colorize, or recognize objects
- But we can't really "brute force" computer vision. Still, it's nice to get an intuition for the size of "image space".

