

Write legibly. Use points, vectors and operators discussed in class, such as $n()$, $U()$, $V()$, $R()$, $+$, $-$, \cdot , i , b , k ... You may use shortcut pseudocode constructions such as “for (each edge (A,B) of polygon P) if...”

1) <3 points> The topological operators i , b , k ... discussed in class should be interpreted with respect to the set \mathbf{R} of real numbers. Let $S = [1] +]2,3[+]3,4[$. Write (in simplest form) of the following sets:

$$S.b = [1] + [2] + [3] + [4]$$

$$S.i =]2,3[+]3,4[$$

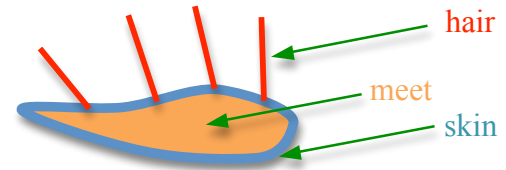
$$S.r = [2,4]$$

2) <3 points> Provide topological definitions of the hair, skin, meet parts of the closed set S shown below.

$$\text{hair} = S - S.r$$

$$\text{meet} = S.i$$

$$\text{skin} = S.i.b$$



3) <2 points> Let B be a ball and T a table. Both are regularized sets. Provide a topological condition that characterizes physically plausible arrangements where the ball touches the table, without interfering with it.

$$(B.i \ T.i == \emptyset) \ \&\& \ (B \ T != \emptyset)$$

Other formulations may also be correct, for instance: $(B.i \cap T.i == \emptyset) \ \&\& \ (B.b \cap T.b != \emptyset)$

4) <1 points> Provide the code for testing whether the polygonal path $\{A,B,C\}$ turns towards the right at B .

```
boolean right(pt A, pt B, pt C) { return  $R(AB) \cdot BC > 0$  }
```

Also acceptable are: $R(AB) \cdot AC > 0$ and $\text{dot}(R(V(A,B)), V(A,C)) > 0$...

5) <3 points> Points A , B , C are in the plane. Provide the code for testing whether point B lies inside the closed edge (A,C)

```
boolean PinE(pt A, pt B, pt C) { return  $(R(AC) \cdot AB == 0) \ \&\& \ (BA \cdot BC \leq 0)$  }
```

6) <2 points> Points Q , R , A , and B , are in the plane. Provide the code for testing whether edge (Q,R) crosses edge (A,B) .

```
boolean ExE(pt Q, pt R, pt A, pt B) {return  $(\text{right}(Q,R,A) != \text{right}(Q,R,B)) \ \&\& \ (\text{right}(A,B,Q) != \text{right}(A,B,R))$  }
```

7) <2 points> Provide the algorithm for finding a “clean” point R such that edge (Q,R) does not hit any vertex of polygon P . You may assume that P fits inside a disk of radius r .

```
pt clean(pt Q, poly P, float r) { pt R=pt(0,0); // initialization
  repeat {
    R=pt(r,random(r)*PI); // keep picking random point R until you find a clean ray (infinite loop?)
    boolean hit=false; // used to track whether ray hits any vertex
    for (each vertex V of P) if PinE(Q,V,R) hit=true; // hit is set if any vertex is hit
    if(!hit) return R; } // if no vertex was hit: return R (we expect that this will happen after one or a few trials!
}
```

8) <4 points> Provide the algorithm for testing whether point Q is inside polygon P . You may use primitive operations, such as $n()$, $U()$, $V()$, $R()$, and also the $\text{right}()$, $\text{PinE}()$, and $\text{ExE}()$ functions defined above. If you need other functions, please provide their code. You may assume that P fits inside a disk of radius r and that Q is not in $P.b$.

```
boolean PinP(pt Q, poly P, float r) {
  boolean in = false; // parity toggle
  pt R = clean(Q,P,r); // finds R outside of P such that Edge(Q,R) does not hit any vertex of P
  for (each edge (A,B) of P) if ExE(Q,R,A,B) in=!in; // toggle when ray intersects edge(A,B)
  return in; }
```