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# Parallel Sort-Merge Join





## Parallel Join Algorithms

• Perform a join between two relations on multiple threads simultaneously to speed up operation.

- Two main approaches:
  - Hash Join
  - Sort-Merge Join

## Hash Join

#### • Phase 1: Partition (optional)

- Divide the tuples of  $\underline{\mathbf{R}}$  and  $\underline{\mathbf{S}}$  into sets using a hash on the join key.
- Phase 2: Build
  - Scan relation **<u>R</u>** and create a hash table on join key.

#### • Phase 3: Probe

For each tuple in  $\underline{S}$ , look up its join key in hash table for  $\underline{R}$ . If a match is found, output combined tuple.

#### • Reference

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## Hashing vs. Sorting

- 1970s Sorting (External Merge-Sort)
- 1980s Hashing (Database Machines)
- 1990s Equivalent
- 2000s Hashing (For Unsorted Data)
- 2010s Hashing (Partitioned vs. Non-Partitioned)
- 2020s ???

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# Today's Agenda

- Background
- Sort Phase
- Merge Phase
- Evaluation
- Retrospective

# Background

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## Single Instruction Multiple Data (SIMD)

- A class of <u>CPU instructions</u> that allow the processor to perform the same operation on multiple data points simultaneously.
- All major ISAs have microarchitecture support SIMD operations.
- We first bring data into SIMD registers and then invoke the appropriate operation.

- ▶ <u>x86:</u> MMX, SSE, SSE2, SSE3, SSE4, AVX
- PowerPC: Altivec
- ARM: NEON

#### SIMD Example







## SIMD Example



## SIMD Example



#### SIMD Trade-Offs

#### Advantages

Significant performance gains and resource utilization if algorithm can be vectorized

#### • Disadvantages

- Implementing an algorithm in SIMD is still mostly a manual process
- SIMD may have restrictions on data alignment
- Gathering data into SIMD registers and scattering to the correct location is tricky

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## Sort-Merge Join

- Phase 1: Sort
  - Sort the tuples of **<u>R</u>** and **<u>S</u>** based on the join key.
- Phase 2: Merge
  - Scan the sorted relations and compare tuples.
  - ► The outer relation **<u>R</u>** only needs to be scanned once.

# Sort-Merge Join



# Sort-Merge Join



## Parallel Sort-Merge Join

- Sorting is the most expensive part.
- Warning: We will be using merge sort for sorting the data.
- Use hardware correctly to speed up the join algorithm as much as possible.
  - Utilize as many CPU cores as possible.
  - Be mindful of NUMA boundaries.
  - Use SIMD instructions where applicable.
- These techniques also apply to the ORDER BY operator.
- Reference

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#### Parallel Sort-Merge Join

#### • Phase 1: Partitioning (optional)

- Partition <u>R</u> and assign them to workers / cores.
- Phase 2: Sort
  - Sort the tuples of **<u>R</u>** and **<u>S</u>** based on the join key.
- Phase 3: Merge
  - Scan the sorted relations and compare tuples.
  - ► The outer relation **<u>R</u>** only needs to be scanned once.

# **Partitioning Phase**

#### Approach 1: Implicit Partitioning

- The data was partitioned on the join key when it was loaded into the database.
- No extra pass over the data is needed.

#### • Approach 2: Explicit Partitioning

Divide only the outer relation and redistribute among the different CPU cores.

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Can use the same radix partitioning approach we talked about last time.

# Sort Phase

#### Sort Phase

- Create <u>runs</u> of sorted chunks of tuples for both input relations.
- It used to be that quick-sort was good enough in disk-centric DBMSs.
- We can explore other methods that try to take advantage of NUMA and parallel architectures.

## **Cache-Conscious Sorting**

#### • Level 1: In-Register Sorting

Sort <u>**runs</u>** that fit into CPU registers.</u>

#### • Level 2: In-Cache Sorting

- Merge Level 1 output into runs that fit into CPU caches.
- Repeat until sorted runs are  $\frac{1}{2}$  cache size.

#### • Level 3: Out-of-Cache Sorting

Used when the runs of Level 2 exceed the size of caches.

## **Cache-Conscious Sorting**



- Abstract model for sorting keys.
  - Fixed wiring **paths** for lists with the same number of elements.
  - Efficient to execute on modern CPUs because of limited data dependencies and no branches.

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#### Level 1 – Sorting Networks

```
wires = [9,5,3,6]
wires[0] = min(wires[0], wires[1])
wires[1] = max(wires[0], wires[1])
wires[2] = min(wires[2], wires[3])
wires[3] = max(wires[2], wires[3])
wires[0] = min(wires[0], wires[2])
wires[2] = max(wires[0], wires[2])
wires[1] = min(wires[1], wires[3])
wires[1] = min(wires[1], wires[3])
wires[2] = max(wires[1], wires[2])
wires[2] = max(wires[1], wires[2])
```



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Instructions:  $\rightarrow$  4 LOAD









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#### Level 2 – Bitonic Merge Network

• Like a Sorting Network but it can merge two locally-sorted lists into a globally-sorted list.

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- Can expand network to merge progressively larger lists up to  $\frac{1}{2}$  LLC size.
  - ► 2.25–3.5× speed-up over SISD implementation.

#### Level 2 – Bitonic Merge Network



## Level 3 – Multi-Way Merging

- Use the Bitonic Merge Networks but split the process up into tasks.
  - Still one worker thread per core.
  - Link together tasks with a **cache-sized FIFO queue**.
- A task blocks when either its input queue is empty, or its output queue is full.
- A thread jumps around whenever work is available at an operator in the pipeline.

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# Level 3 – Multi-Way Merging



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# Merge Phase

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## Merge Phase

- Iterate through the outer table and inner table in lockstep and compare join keys.
- May need to backtrack if there are duplicates.
- Done in parallel at the different cores.

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#### Sort-Merge Join Variants

- Multi-Way Sort-Merge (<u>M-WAY</u>)
- Multi-Pass Sort-Merge (M-PASS)
- Massively Parallel Sort-Merge (<u>MPSM</u>)

#### • Outer Table

- Each core sorts in parallel on local data (levels 1/2).
- Redistribute sorted runs across cores using the multi-way merge (level 3).

#### • Inner Table

- Same as outer table.
- Merge phase is between matching pairs of chunks of outer/inner tables at each core.

• Reference



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## Multi-Pass Sort-Merge

#### <u>Outer Table</u>

- Same level 1/2 sorting as Multi-Way.
- But instead of redistributing, it uses a multi-pass naïve merge on sorted runs.

#### • Inner Table

- Same as outer table.
- Merge phase is between matching pairs of chunks of outer table and inner table.
- The hardware prefetcher masks the latency penalty of going over NUMA regions.

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#### Multi-Pass Sort-Merge



#### <u>Outer Table</u>

- **Range-partition** outer table and redistribute to cores.
- Each core sorts in parallel on their partitions.

#### • Inner Table

- Not redistributed like outer table.
- Each core sorts its local data.
- Merge phase is between entire sorted run of outer table and a segment of inner table.

• Reference



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### **Rules for Parallelization**

- <u>Rule 1</u>: No random writes to non-local memory
  - Chunk the data, redistribute, and then each core sorts/works on local data.
- Rule 2: Only perform sequential reads on non-local memory
  - ► This allows the hardware prefetcher to hide remote access latency.
- **<u>Rule 3</u>**: No core should ever wait for another
  - Avoid fine-grained latching or sync barriers.

# Evaluation

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#### Evaluation

- Compare the different join algorithms using a synthetic data set.
  - Sort-Merge: M-WAY, M-PASS, MPSM
  - Hash: Radix Partitioning
- Hardware:
  - 4 Socket Intel Xeon E4640 @ 2.4GHz
  - 8 Cores with 2 Threads Per Core
  - 512 GB of DRAM

# Raw Sorting Performance

#### Single-threaded sorting performance



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## **Raw Sorting Performance**

- STL's sort is a hybrid algorithm
- Quicksort in the beginning, and then switches over to Heapsort.

## Comparison of Sort-Merge Joins

Workload: 1.6B ≈ 128M (8-byte tuples)



## Comparison of Sort-Merge Joins

- Multi-way performs the best.
- Does more work to redistribute data.
- But it enables better cache locality  $\implies$  higher number instructions per cycle.

## M-way Join vs. MPSM Join



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## M-way Join vs MPSM Join

- M-WAY: Extra instructions used for the multi-way sort in Level 3 pays off.
- MPSM: Overhead of reading data across NUMA regions hurts performance
- Hardware prefetcher is unable to help in this case.

#### Sort-Merge Join vs. Hash Join



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## Sort-Merge Join vs. Hash Join

- Hash join works well in all settings.
- Radix partitioning overhead is high since the tables are large.
- No partitioning scheme should do even better.

#### Sort-Merge Join vs. Hash Join



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#### Sort-Merge Join vs. Hash Join

- Radix hash needs more passes with larger tables.
- Performance gap shrinks due to partitioning overhead.
- No partitioning scheme should do even better.

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# Summary

- Both join algorithms are equally important.
- Every serious OLAP DBMS supports both.
- Sort-merge join is useful when the output needs to be sorted.

# Retrospective

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## What did we learn

- You are tired of systems programming
- You are exhausted
- Let's take a step back and think about what happened

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#### Lessons learned

- Systems programming is hard
- Become a better programmer through the study of database systems internals
- Going forth, you should have a good understanding how systems work

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# **Big Ideas**

- Database systems are awesome but are not magic.
- Elegant abstractions are magic.
- Declarativity enables usability and performance.
- Building systems software is more than hacking
- There are recurring motifs in systems programming.
- CS has an intellectual history and you can contribute.

#### What Next?

- We have barely scratched the surface. Follow-on course: CS 8803 (DBMS Implementation Part II)
  - Query Compilation + Vectorization
  - Query Optimization
  - Concurrency Control
  - Logging and Recovery Methods
- Stay in touch
  - ► Tell me when this course helps you out with future courses (or jobs!)
  - Ask me cool DBMS questions

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# Parting Thoughts

- You have surmounted several challenges in this course.
- You make it all worthwhile.
- Please share your feedback via CIOS.