

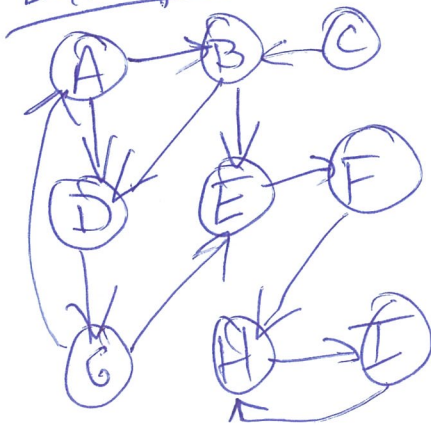
DFS = Depth first search

We used DFS for:

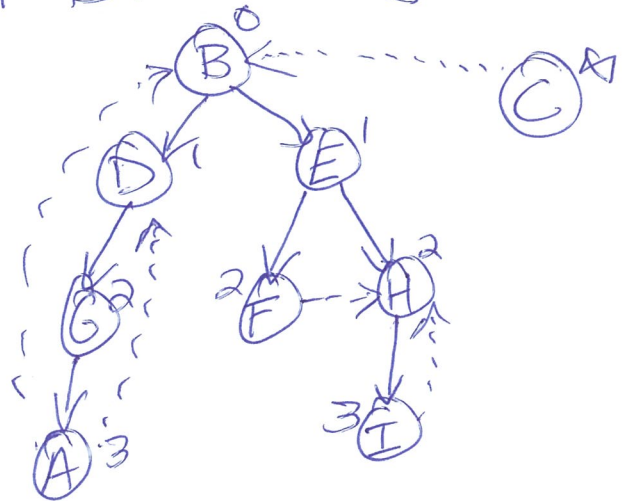
- 1) connected components of undirected graphs
- 2) topological sorting of DAGs
- 3) strongly connected components (SCCs) of directed graphs

BFS = breadth first search
= explore graph in layers

Example:



Run BFS starting at B:



BFS(G, s)

input: $G=(V, E)$ in adj. list. representation $\left(\begin{array}{l} G \text{ can be} \\ \text{directed or} \\ \text{undirected} \end{array} \right)$

output: for all $w \in V$, $\text{dist}(w) = \min \# \text{ of edges to go from } s \text{ to } w$

for all $w \in V$, $\text{dist}(w) = \infty$

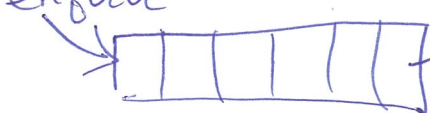
$\text{dist}(s) = 0$

$Q = \{s\}$ (create a new queue just containing $\{s\}$)

While $Q \neq \emptyset$

$\left[\begin{array}{l} w = \text{dequeue}(Q) \\ \text{for all } (w, z) \in E \\ \quad \left[\begin{array}{l} \text{if } \text{dist}(z) = \infty \\ \quad \text{then } \left[\begin{array}{l} \text{enqueue}(Q, z) \\ \text{dist}(z) = \text{dist}(w) + 1 \end{array} \right] \end{array} \right. \end{array} \right]$

Running time: $O(|V| + |E|) = O(n + m)$

Queue: 

FIFO = first-in first-out.

③

Generalize BFS to allow Positive lengths on edges.

Let $l(e)$ = length of edge e .
 $l(e) > 0$.

For a path $P: w_0 \rightarrow w_1 \rightarrow w_2 \rightarrow \dots \rightarrow w_k$

its length is: $l(P) = \sum_{i=0}^{k-1} l(w_i, w_{i+1})$

$\text{dist}(v, w)$ = length of shortest path from v to w

$= \min_P \{ l(P) : P \text{ is a path from } v \text{ to } w \}$

Goal: for given $s \in V$, find $\text{dist}(s, w)$
for all $w \in V$.

BFS solves it when $l(e) = 1$ for all $e \in E$.

④

Suppose every $l(e)$ is a positive integer.

For every edge e , replace e by a path of length $l(e)$ & give each new edge length 1.

Run BFS on this new graph.

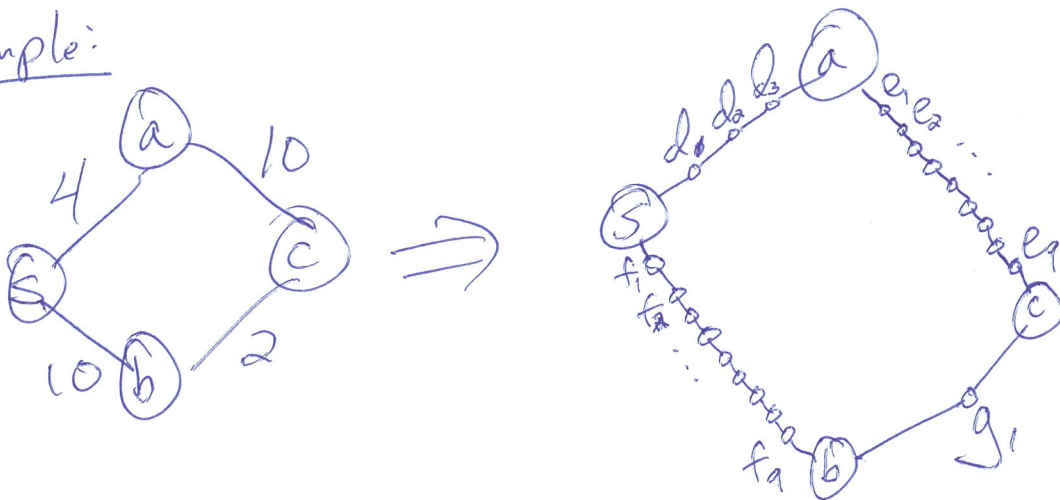
Problem: running time depends on lengths $l(e)$ which might be HUGE.

Most of the time BFS is processing "dummy" vertices that we added.

Can we skip such times & only consider times to process original vertices?

Set "alarm clocks" for times of interest.

Example:



(5)

time 0: see s

1: see d_1 & f_1

2: see d_2 & f_2

3:

→ 4: see a & f_4

⋮

→ 10: see b & e_6

⋮

→ 12: see c

idea: each vertex w has an alarm clock set at $Q(w)$
when we see a new path to w , check if
need to adjust w 's clock.

High-level algorithm:

Initialize: for s set its alarm for $Q(s) = 0$

for all $w \in V - s$, set $Q(w) = \infty$

Repeat until no more alarms (ignore ~~no~~-time alarms)

Let w be the next alarm clock to
go off at time T .

Then: set $\text{dist}(w) = T$

for every $(w, z) \in E$:

if $Q(z) > T + l(w, z)$

then $Q(z) = T + l(w, z)$.

⑥

To implement alarm clocks, use min-heaps data structure
↑
priority queue.

Min-heap data structure H :

H contains a set of elements (in our case, element = vertex)
each element has a key (in our case, $\text{Key} = \text{dist}(w)$)

Operations:

$\text{Insert}(H, w, \text{dist}(w)) =$ add element w with key $\text{dist}(w)$ to H

$\text{DecreaseKey}(H, w, \text{dist}(w)) =$ for $w \in H$, decrease its key to $\text{dist}(w)$

$\text{DeleteMin}(H) =$ output the element in H with smallest
& delete it from H

For a heap with $\leq n$ elements,
 $O(\log n)$ time per operation.

Dijkstra(G, l, s)

(7)

input: $G=(V, E)$ with $l(e) > 0$ for each $e \in E$
& vertex $s \in V$

output: for all $w \in V$,

$\text{dist}(w)$ = length of shortest $s \rightarrow w$ path

$\text{prev}(w)$ = parent of w on this $\nearrow$ path

for all $w \in V$, $\left[\begin{array}{l} \text{dist}(w) = \infty \\ \text{prev}(w) = \text{NULL} \end{array} \right.$

$\text{dist}(s) = 0$

$H = \emptyset$

for all $w \in V$, $\text{Insert}(H, w, \text{dist}(w))$

while $H \neq \emptyset$:

$w = \text{deletemin}(H)$

for all $(w, z) \in E$:

if $\text{dist}(w) > \text{dist}(w) + l(w, z)$

then: $\left[\begin{array}{l} \text{dist}(z) = \text{dist}(w) + l(w, z) \\ \text{prev}(z) = w \end{array} \right.$

$\text{DecreaseKey}(H, z, \text{dist}(z))$

Running time:

n inserts & n deletes $\Rightarrow O(n \log n)$ time.

$\leq m$ decrease keys $\Rightarrow O(m \log n)$ time

$\Rightarrow O((n+m) \log n)$ total time.

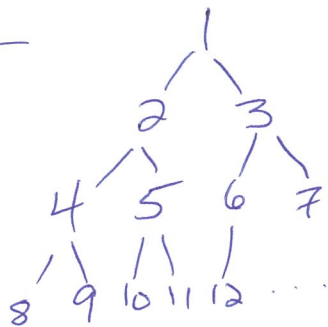
if G is connected then

$m \geq n-1$, so it's $O(n \log n)$ total time.

How to implement min-heaps?

Use complete binary tree: every level is full except possibly the bottom level
fill bottom level from left to right

Example:



Can use an array $A[1 \dots 12]$ to store the keys for tree

For node in position i of $A[1]$

Parent is in position $\lfloor \frac{i}{2} \rfloor$

left child is at $2i$,

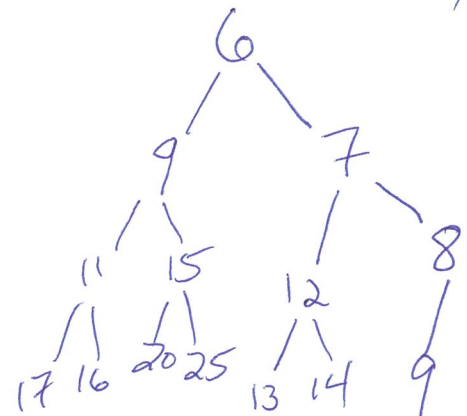
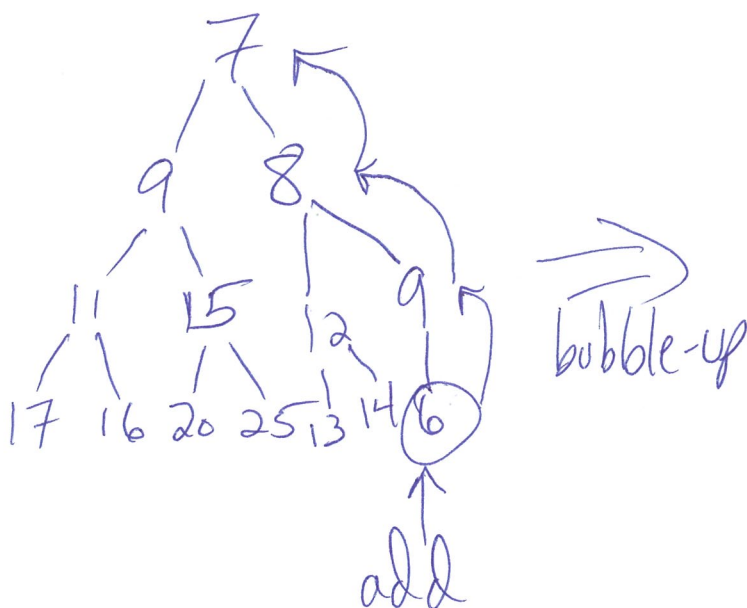
right child is at $2i+1$.

$$\text{let } p(i) = \lfloor \frac{i}{2} \rfloor$$

Min-heap property: $A[p(i)] \leq A[i]$

Min key is at root.

Insert: add new element to
bottom level, leftmost open spot
this maintains desired shape
then "bubble-up" to maintain
min-heap property



To decrease-key: lower its value & then
Bubble-up

To delete-Min:

- 1) output value at root
- 2) Delete root
- 3) Take element from bottom-right & put it at the root
- 4) Sift-down:

Example:-

