

- What's NP-completeness mean?
 - What's $P=NP$ or $P \neq NP$ mean?
 - How do we show that a problem is intractable?
intractable = unlikely to be solved efficiently
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P = class of all search problems that
are solvable in polynomial time

NP = class of all search problems
(regardless of time required to
solve them)

What's a search problem?

Roughly, Problem where we can
efficiently verify solutions.

So, $P=NP$ or $P \neq NP$ addresses whether or not:

Solving a Problem (i.e., constructing a solution)	is as easy as	Verifying a solution
P	?	NP

Formally what is a search problem?

Search problem:

Given instance I (for example graph G)

We are asked to find a solution if one exists

and if no solution exists we output NO.

Further to be a search problem

if we are given a solution S

we can verify (check) in

time polynomial in $|I|$

that S is a solution to I .

In other words, when there is a solution,
given such a solution we can check it
is a solution, efficiently

If there are NO solutions then we don't
need to do anything.

Efficiently means $\text{Poly}(I)$

Thus we need that the solution $|S| \leq \text{Poly}(I)$

& we need to show an algorithm A
that takes I & S as input
and in Polynomial-time verifies
that S is a solution to I.

Examples of search Problems:

k-coloring:

input: $G = (V, E)$ ^{undirected} & integer $k \geq 0$
output: Assign each vertex a color in $\{1, \dots, k\}$

so that adjacent vertices get
different colors.

and NO if no such k-coloring
exists for G.

Given G & a k-coloring in $O(|V| + |E|)$ time
we can verify that it is a valid coloring.

Hence, Coloring $\in \text{NP}$.

SAT:

input: Boolean formula f in CNF with n variables & m clauses

output: Satisfying assignment if one exists
NO otherwise

What's this mean?

Variables x_1, x_2, \dots, x_n which take values TRUE or FALSE

Literals $x_1, \bar{x}_1, x_2, \bar{x}_2, \dots, x_n, \bar{x}_n$

\wedge = and

\vee = or

clause is the OR of some literals

example: $(x_2 \vee \bar{x}_4 \vee x_1)$

so either $x_2=T$ or $x_4=F$ or $x_1=T$

f in CNF is the AND of m clauses:

example: $(\bar{x}_2) \wedge (x_2 \vee \bar{x}_4 \vee x_1) \wedge (x_3 \vee x_2 \vee \bar{x}_1)$

SAT ENP

Why? Given f and an assignment,
in $O(n)$ time per clause we can verify that
each clause is satisfied

& hence in $O(m)$ total time we can verify that
the assignment satisfies f . \square

Knapsack:

input: n objects with
 integer weights w_1, \dots, w_n
 & integer values v_1, \dots, v_n
 Capacity B

output: subset S of objects with
 total weight $\leq B$
 & maximum total value.

Given instance $\{w_1, \dots, w_n, v_1, \dots, v_n, B\}$
 & solution S ,

We can verify in $O(n)$ time that the
 total weight is $\leq B$

but how do we verify that it
 has maximum value?

(need to do it in $\text{Poly}(n, \log B)$)

Not clear how to do it.

This is an optimization problem.

Look at Search version:

input: $w_1, \dots, w_n, v_1, \dots, v_n, B$ & goal g .
 as before

output: subset S with
 total weight $\leq B$ ($\sum_{i \in S} w_i \leq B$)
 & total value $\geq g$ ($\sum_{i \in S} v_i \geq g$)
 & NO if no such S exists.

Given S , in $O(n)$ time can check that it
 has total weight $\leq B$
 & total value $\geq g$.
 \Rightarrow Knapsack-search $\in NP$.

Note: if we can solve the search version
 in poly-time then we can solve
 the optimization version in poly-time
 by doing binary search for
 $\max g\{1, \dots, V\}$ which has a solution
 where $V = \sum_{i=1}^n v_i$

MST:

input: $G = (V, E)$ with positive edge lengths
output: tree T with min weight

MST is a search problem.

Hence, MST \in NP.

Why?

Given $G \& T$ we can run Kruskal's or Prim's

to verify that T has min weight

& then run BFS or DFS to verify that
 T is a tree.

NP stands for nondeterministic Polynomial time.

= problems that can be solved in

Poly-time on a nondeterministic machine.



allowed to guess at each step
 (There exists a path to the accepting state)

$NP =$ all search problems

$P =$ search problems that can be solved in poly-time

Hence $P \subset NP$



if $P = NP$:

means that if we can verify solutions efficiently
 then we can construct solutions efficiently
 (e.g., ~~is~~ verifying a proof for a theorem
 is as hard as constructing a proof)

if $P \neq NP$: then there are some
 search problems that can't be
 solved in poly-time.

What are these problems?

NP-complete problems: hardest problems in NP.

Colorings is NP complete.

⑨

This means:

a) Colorings \in NP

b) if we can solve colorings in Poly-time
then we can solve every problem in NP
in Poly-time.

Thus if $P \neq NP$ then there is no Poly-time algorithm for colorings.

How to show (b)?

Reductions:

Problems A & B (example $A = MST$
 $B = \text{Colorings}$)

$A \rightarrow B$ or $A \leq B$

Means we can reduce A to B.

$A \rightarrow B$ means that:

if we can solve B in Poly-time then
we can use that algorithm to solve A
in Poly-time.

So we suppose there is an efficient algorithm for B
and we use that algorithm as a black-box
to solve A.

In other words:

take input I for A (that we want to solve)

1) create input $f(I)$ for B

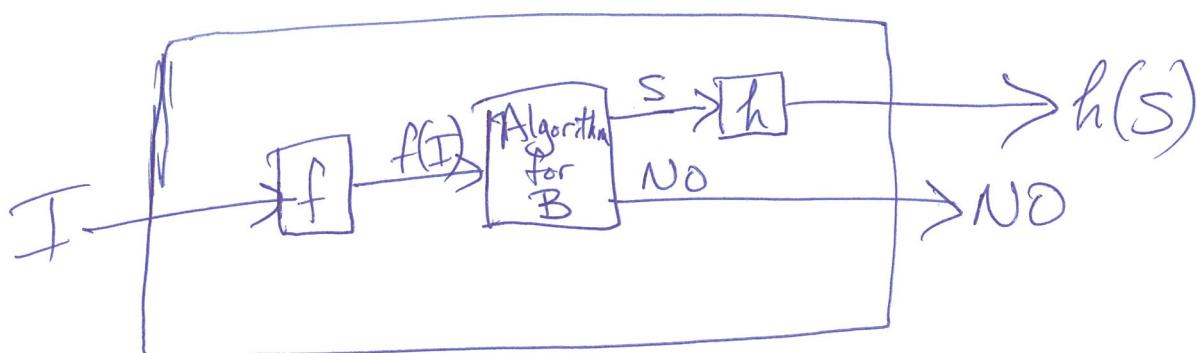
2) Run blackbox algorithm for B

3) Given solution S for $f(I)$

we convert it to get
solution $h(S)$ for I

& given NO for $f(I)$

we output NO for I.



We need to define f & h

& prove that if S is a solution to $f(I)$
Then $h(S)$ is a solution to I

& if NO solution for $f(I)$

then NO solution for I

To show: Colorings is NP-complete

We need to show:

a) Colorings \in NP

b) for all $A \in$ NP,
 $A \rightarrow$ Colorings

How to do (b) for all $A \in$ NP?

Suppose we know SAT is NP-complete.

Hence we know that for every $A \in \text{NP}$

$$A \rightarrow \text{SAT}.$$

If we show $\text{SAT} \rightarrow \text{Colorings}$

then $A \rightarrow \text{SAT} \rightarrow \text{Colorings}$

So $A \rightarrow \text{Colorings}$.

To show Colorings is NP-complete
we need to show:

a) Colorings $\in \text{NP}$

b) for a known