

# ViperGPT: Visual Inference via Python Execution for Reasoning

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# Outline

- Problem Statement
- Related Works
- Approach
- Experiments & Results
- Limitations, Societal Implications
- Summary of Strengths, Weaknesses, Relationship to Other Papers

# Problem Statement: VLM Reasoning Tasks

- Visual Grounding
  - Identifying the bounding box in an image that corresponds best to a given query.
- Compositional Image Question Answering
  - Decomposing complex questions into simpler tasks.
- External Knowledge-dependent Image Question Answering
  - Many questions about images can only be answered correctly by integrating outside knowledge about the world.



Query: pizza front



Query: Does that pancake look brown and round?



Query: The real live version of this toy does what in the winter?

# Problem Statement



- Query: How many muffins can each kid have for it to be fair?
  - 1) Find the children and the muffins in the image
  - 2) Count how many there are of each
  - 3) Reason that 'fair' implies an even split, hence divide.

End-to-end models do not inherently leverage compositional reasoning.

- They fail to make use of
  - Advances in fundamental vision tasks at different steps
  - Computers can perform mathematical operations (e.g., division) easily without machine learning
- Uninterpretable decisions
  - No way to audit the result of each step to diagnose failure
  - Model becomes increasingly untenable as the data and computation grow

# Problem Statement: ViperGPT

- Interpretability
  - Explicit code function calls for each step
  - Intermediate values that can be inspected
- Flexibility: Easily incorporate any vision or language module
- Composability: Decompose tasks into smaller sub-tasks performed step-by-step
- Training-free: Recombine existing models in new ways without additional training
- Generalizability: Unify all tasks into one system

Query: How many muffins can each kid have for it to be fair?



## Generated Code

```
def execute_command(image):  
    image_patch = ImagePatch(image)  
    muffin_patches = image_patch.find("muffin")  
    kid_patches = image_patch.find("kid")  
    return str(len(muffin_patches) // len(kid_patches))
```

## Execution

```
muffin_patches =  
image_patch.find("muffin")
```



```
kid_patches =  
image_patch.find("kid")
```



```
► len(muffin_patches)=8  
► len(kid_patches)=2
```

```
► 8//2 = 4
```

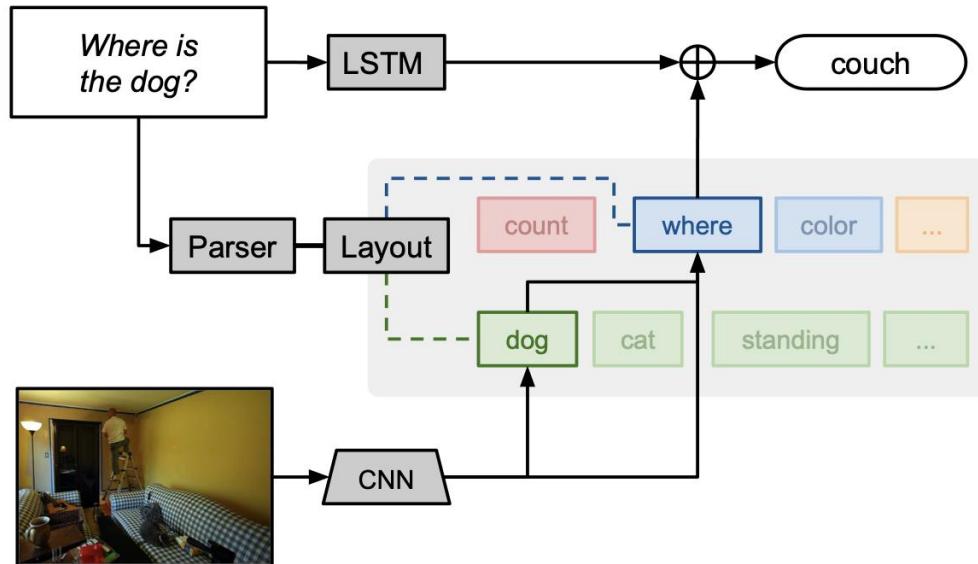
```
Result: 4
```



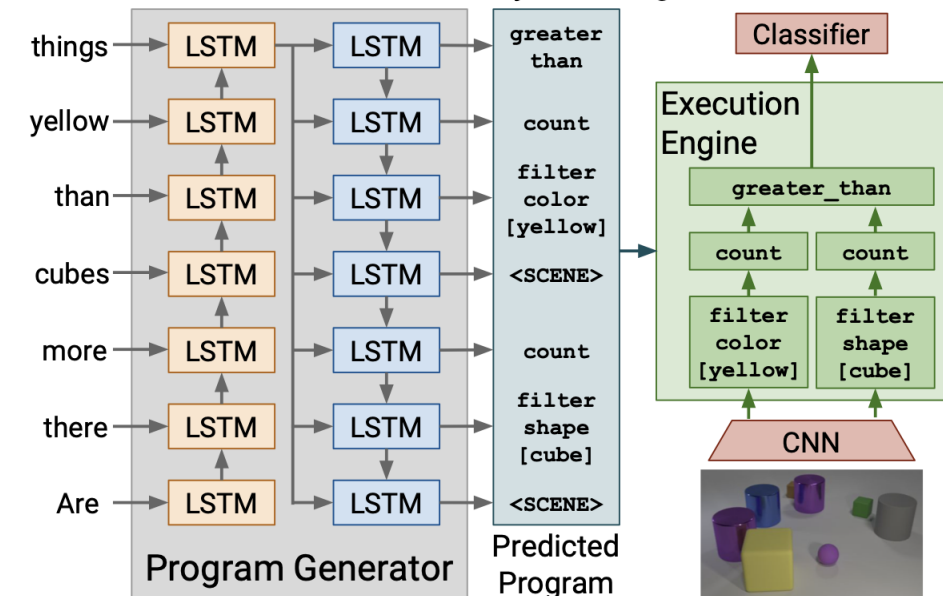
# Related Works

# Related Works: Neural Module Networks

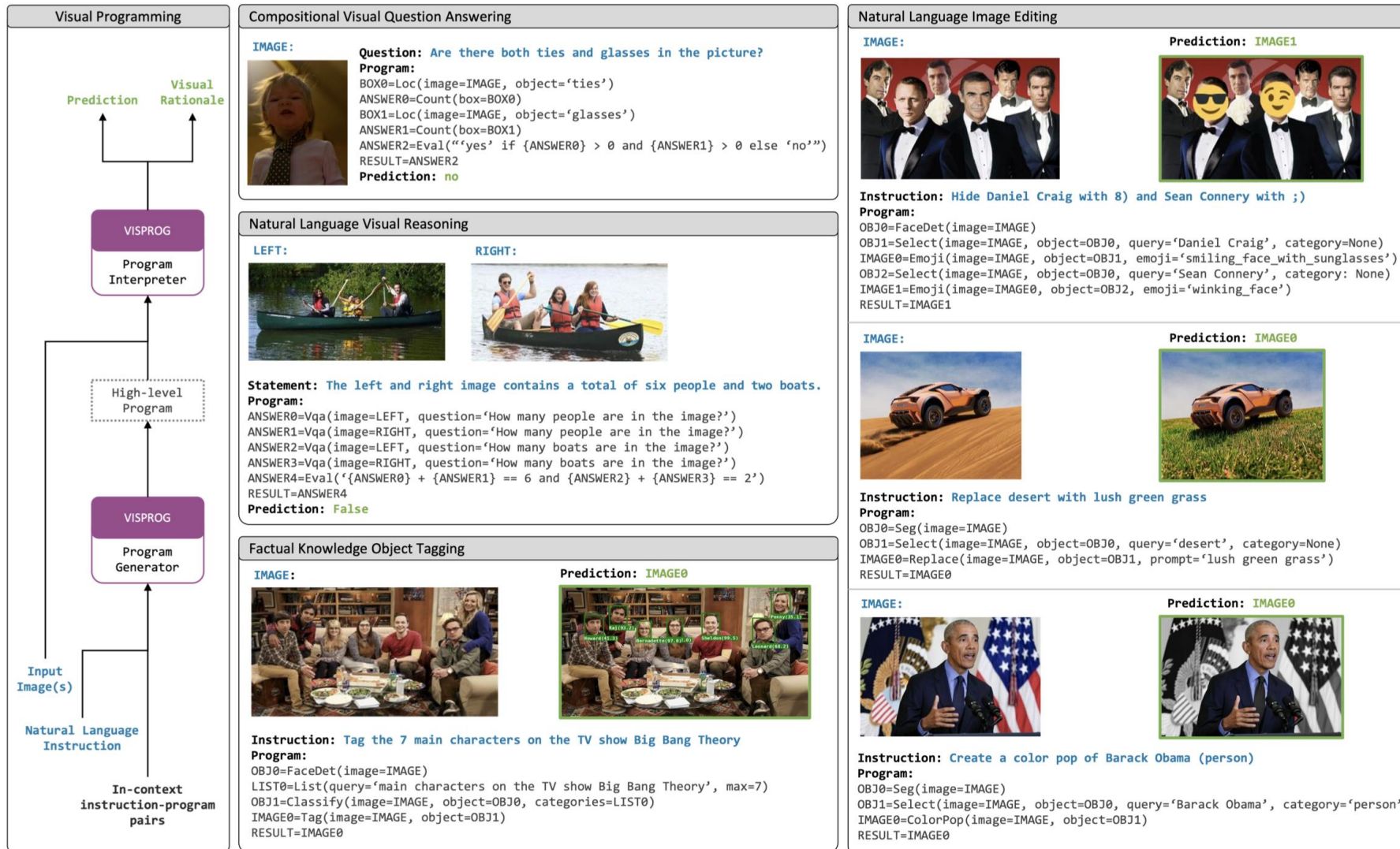
- Intuition: decompose tasks into simpler modules
  - Training end-to-end with modules rearranged in different ways for different problems
  - Each module would learn their appropriate function
- Cons
  - Expensive supervision in the form of programs → domain-limited
  - End-to-end training: learn the perceptual models jointly with the program generator → fail to produce the intended modular structure



**Question:** Are there more cubes than yellow things? **Answer:** Yes



# Related Works: Automatic Module Integration Using LLMs



ViperGPT: directly generate unrestricted Python code

## VISPROG

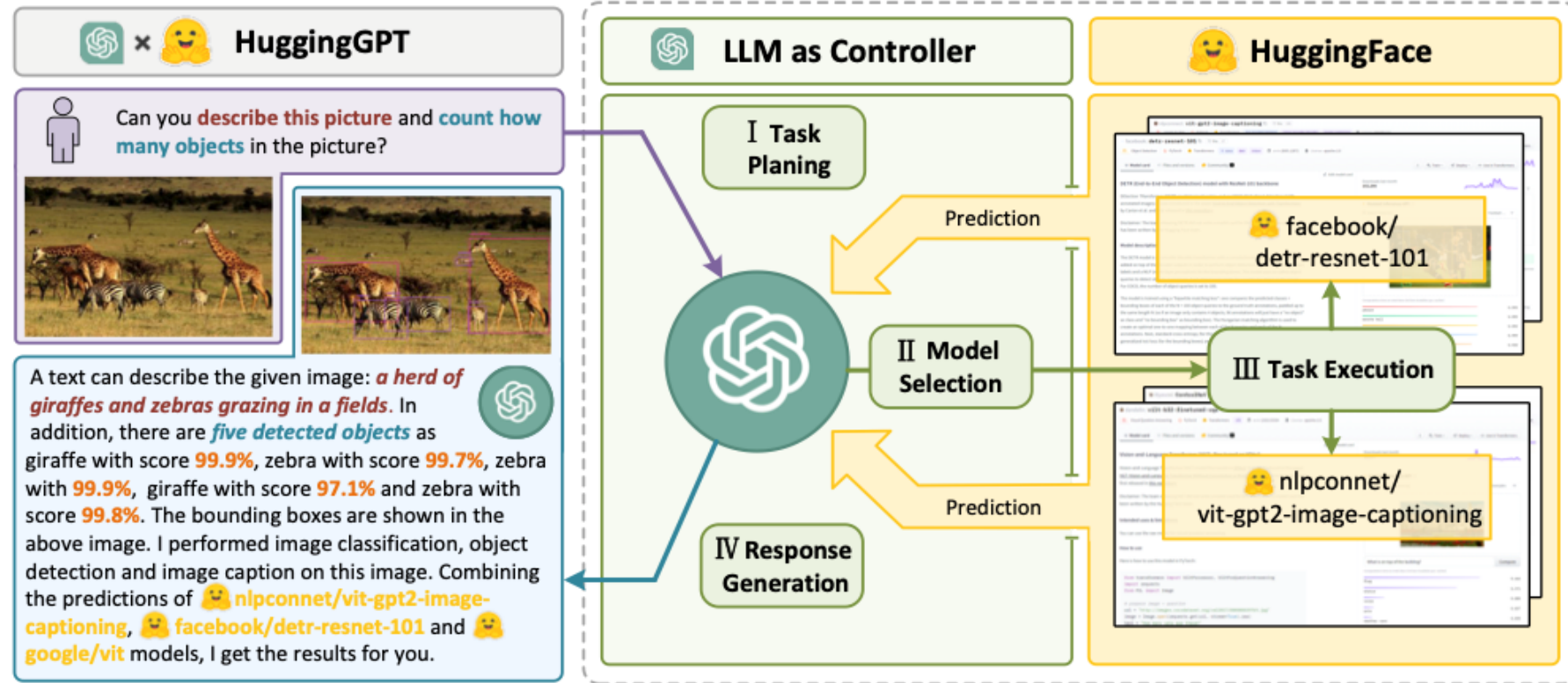
- Generates a list of pseudocode instructions which needs further interpretation

Very similar ideas. VISPROG was ~4 months earlier but went unnoticed due to CVPR publicity restrictions.



# Related Works: HuggingGPT

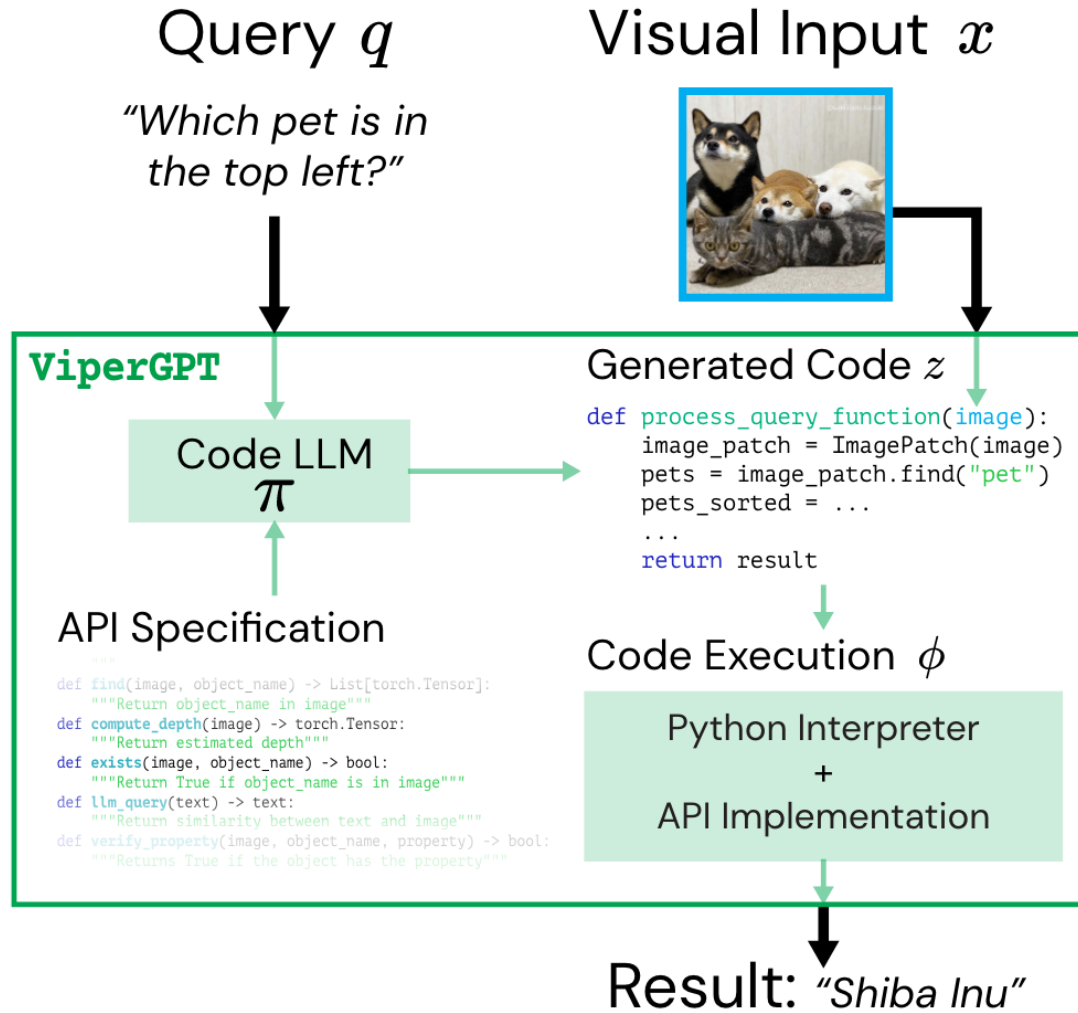
- 4 step process:
  - Decompose request into tasks with dependencies
  - Assign models for each task
  - Execute tasks via HuggingFace
  - Synthesize information into one response
- Similar reasoning approach to ViperGPT, but with more tools
- Structured natural language instead of code



```
[{"task": "pose-detection", "id": 0, "dep": [-1], "args": {"image": "e3.jpg"}}, {"task": "pose-text-to-image", "id": 1, "dep": [0], "args": {"text": "a girl reading a book", "image": "<re-source>-0"}}
```

# Approach

# Approach: Overview



- ViperGPT is a framework for solving complex visual queries programmatically.
- Inputs
  - Visual input  $x$ : image / videos
  - Textual query  $q$ : questions or descriptions
- Output  $r$ : any type (e.g., text / image crops)
- Program generator  $\pi$ :  $z = \pi(q)$ 
  - $\pi$ : LLMs
  - $z$ : Python code
- Execution engine  $\phi$ :  $r = \phi(x, z)$ 
  - Python Interpreter
  - API Implementation



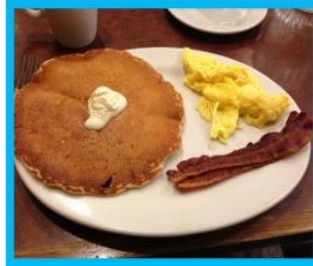
# Approach: Program Generation

**Query:** Does that pancake look brown and round?

Generated code

```
def execute_command(image):  
    image_patch = ImagePatch(image)  
    pancake_patches = image_patch.find("pancake")  
    is_brown = pancake_patches[0].verify_property("pancake", "brown")  
    is_round = pancake_patches[0].verify_property("pancake", "round")  
    return bool_to_yn(is_brown and is_round)
```

In:



**Query:** Are there water bottles to the right of the bookcase that is made of wood?

Generated code

```
def execute_command(image):  
    image_patch = ImagePatch(image)  
    bookcase_patches = image_patch.find("bookcase")  
    for bookcase_patch in bookcase_patches:  
        is_wood = bookcase_patch.verify_property("bookcase", "wood")  
        if is_wood:  
            water_bottle_patches = image_patch.find("water bottle")  
            for water_bottle_patch in water_bottle_patches:  
                if water_bottle_patch.horizontal_center > \  
                    bookcase_patch.horizontal_center:  
                    return "yes"  
            return "no"  
    return "no"
```

In:



- Program Generator: GPT-3 Codex
  - Obviates the need for task-specific training for program generation.
- Input: a sequence of code text
  - Prompt: API specification
  - Query for the sample under consideration
- Output: Python function definition as a string.



# Approach: Modules - ImagePatch

- Each module is implemented as a class method.

```
1 class ImagePatch:
2     """A Python class containing a crop of an image centered around a particular object, as well as relevant information.
3     Attributes
4     -----
5     cropped_image : array_like
6         An array-like of the cropped image taken from the original image.
7     left : int
8         An int describing the position of the left border of the crop's bounding box in the original image.
9     lower : int
10        An int describing the position of the bottom border of the crop's bounding box in the original image.
11    right : int
12        An int describing the position of the right border of the crop's bounding box in the original image.
13    upper : int
14        An int describing the position of the top border of the crop's bounding box in the original image.
15
16    Methods
17    -----
18    find(object_name: str)->List[ImagePatch]
19        Returns a list of new ImagePatch objects containing crops of the image centered around any objects found in the
20        image matching the object_name.
21    exists(object_name: str)->bool
22        Returns True if the object specified by object_name is found in the image, and False otherwise.
23    verify_property(property: str)->bool
24        Returns True if the property is met, and False otherwise.
25    best_text_match(option_list: List[str], prefix: str)->str
26        Returns the string that best matches the image.
27    simple_query(question: str=None)->str
28        Returns the answer to a basic question asked about the image. If no question is provided, returns the answer
29        to "What is this?".
30    compute_depth()->float
31        Returns the median depth of the image crop.
32    crop(left: int, lower: int, right: int, upper: int)->ImagePatch
33        Returns a new ImagePatch object containing a crop of the image at the given coordinates.
34    """
```

# Approach: Modules - VideoSegment

```
321 class VideoSegment:
322     """A Python class containing a set of frames represented as ImagePatch objects, as well as relevant information.
323     Attributes
324     -----
325     video : torch.Tensor
326         A tensor of the original video.
327     start : int
328         An int describing the starting frame in this video segment with respect to the original video.
329     end : int
330         An int describing the ending frame in this video segment with respect to the original video.
331     num_frames->int
332         An int containing the number of frames in the video segment.
333
334     Methods
335     -----
336     frame_iterator->Iterator[ImagePatch]
337     trim(start, end)->VideoSegment
338         Returns a new VideoSegment containing a trimmed version of the original video at the [start, end] segment.
339     select_answer(info, question, options)->str
340         Returns the answer to the question given the options and additional information.
341     """
```

- Each module is implemented as a class method.

# Approach: API

```
94 def exists(self, object_name: str) -> bool:
95     """Returns True if the object specified by object_name is found in the image, and False otherwise.
96     Parameters
97     -----
98     object_name : str
99         A string describing the name of the object to be found in the image.
100
101     Examples
102     -----
103     >>> # Are there both cakes and gummy bears in the photo?
104     >>> def execute_command(image)->str:
105     >>>     image_patch = ImagePatch(image)
106     >>>     is_cake = image_patch.exists("cake")
107     >>>     is_gummy_bear = image_patch.exists("gummy bear")
108     >>>     return bool_to_yesno(is_cake and is_gummy_bear)
109     """
110     return len(self.find(object_name)) > 0
```

```
310 def llm_query(question: str) -> str:
311     '''Answers a text question using GPT-3. The input question is always a formatted string with a variable in it.
312
313     Parameters
314     -----
315     question: str
316         the text question to ask. Must not contain any reference to 'the image' or 'the photo', etc.
317     '''
318     return llm_query(question)
```

## API specifies

- Input and output types
- Docstrings to explain the purpose of these functions in natural language
- Examples that show how to use these classes and their functions (query-code pairs)

Only specifications, no full implement

- LLM context windows are limited
- Code generation is independent of changes made to the module implementation

# Approach: Program Execution

- Python interpreter: logical operations
- Pretrained model APIs: perceptual operations

**Query:** Does that pancake look brown and round?

Generated code

```
def execute_command(image):  
    image_patch = ImagePatch(image)  
    pancake_patches = image_patch.find("pancake")  
    is_brown = pancake_patches[0].verify_property("pancake", "brown")  
    is_round = pancake_patches[0].verify_property("pancake", "round")  
    return bool_to_yn(is_brown and is_round)
```

In:



Execution

```
pancake_patches = image_patch.  
    find("pancake")  
▶ pancake_patches[0] = {ImagePatch}
```



```
...verify_property("pancake", "brown")  
▶ is_brown = {bool} True
```

```
...verify_property("pancake", "round")  
▶ is_round = {bool} True
```

```
▶ is_brown and is_round = {bool} True  
Result: "yes"
```

**Query:** Are there water bottles to the right of the bookcase that is made of wood?

Generated code

```
def execute_command(image):  
    image_patch = ImagePatch(image)  
    bookcase_patches = image_patch.find("bookcase")  
    for bookcase_patch in bookcase_patches:  
        is_wood = bookcase_patch.verify_property("bookcase", "wood")  
        if is_wood:  
            water_bottle_patches = image_patch.find("water bottle")  
            for water_bottle_patch in water_bottle_patches:  
                if water_bottle_patch.horizontal_center > \  
                    bookcase_patch.horizontal_center:  
                    return "yes"  
            return "no"  
    return "no"
```

In:



Execution

```
bookcase_patches = image_patch.  
    find("bookcase")  
▶ bookcase_patches[0] = {ImagePatch}
```



```
▶ bookcase_patches[0].  
    horizontal_center = {float} 239.0
```

```
...verify_property("bookcase", "wood")  
▶ is_wood = {bool} True
```

```
water_bottle_patches = image_patch.  
    find("water bottle")
```

```
▶ water_bottle_patches[0]  
    = {ImagePatches}
```



```
▶ water_bottle_patches[0].  
    horizontal_center = {float} 608.5
```

```
▶ water_bottle_patch.horizontal_center > \  
    bookcase_patch.horizontal_center = \  
    {bool} True  
Result: "yes"
```



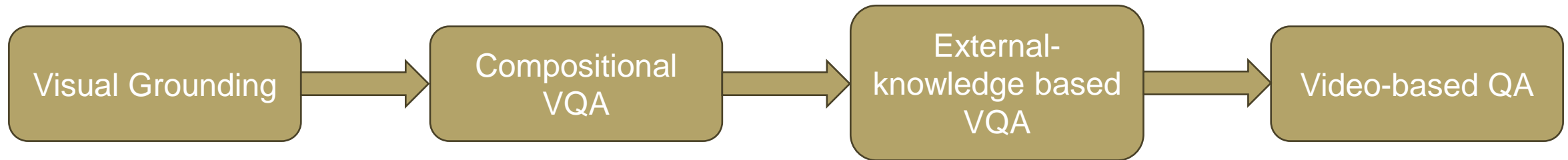
# Approach: Program Execution

- Pretrained Models
  - GLIP: find, exists
  - MiDaS: compute\_depth
  - BLIP-2: simple\_query
  - X-VLM: verify\_property, best\_image\_match, best\_text\_match
  - GPT-3: llm\_query, select\_answer
  - Codex: code generation

# Evaluations and Results

# Evaluations and Results

- Defines 4 main tasks ranging from basic understanding to complex synthesis
- Each task is a "prerequisite" for following task



# Overview of Modules

- **find**: image and noun --> identifies patches containing noun
- **exists**: image and noun --> identifies if noun exists in image
- **verify\_property**: image, noun, and property --> identifies if noun has property in image
- **best\_image\_match**: image patches and noun --> returns image patch matching noun
- **best\_text\_match**: list of nouns and image --> returns noun that matches image
- **compute\_depth**: image patch --> median depth of patch
- **distance**: image patches --> distance between patches
- **simple\_query**: short image/text questions that cannot be decomposed
- **llm\_query**: queries requiring external knowledge
- **select\_answer**: textual information about scene and possible answers --> best answer



# Visual Grounding

- Requires spatial reasoning and object identification
- Modules provided:
  - Find, exists, verify\_property, best\_image\_match, compute\_depth, distance
- Evaluated on RefCOCO and RefCOCO+
- Takeaways:
  - Clearly outperforms zero-shot methods
  - Still far behind fine-tuned models
  - Expected result since this task focuses on visual understanding instead of reasoning

		IoU (%) ↑	
		RefCOCO	RefCOCO+
Sup.	MDETR [53]	90.4	85.5
	OFA [53]	94.0	91.7
ZS	OWL-ViT [38]	30.3	29.4
	GLIP [31]	55.0	52.2
	ReCLIP [49]	58.6	60.5
	<b>ViperGPT (ours)</b>	<b>72.0</b>	<b>67.0</b>

# Compositional VQA

- Requires breaking down complex questions into simpler components
- Modules added:
  - `simple_query`, `best_text_match`
- Evaluated on GQA dataset
- Takeaways:
  - Slightly better than BLIP-2
  - Decently far behind all fine-tuned methods
  - Some emphasis on reasoning, but still largely focusing on spatial understanding

Table 2. **GQA Results**. We report accuracy on the test-dev set.

		Accuracy (%) ↑
Sup.	LGCN [20]	55.8
	LXMERT [51]	60.0
	NSM [24]	63.0
	CRF [39]	72.1
ZS	BLIP-2 [30]	44.7
	<b>ViperGPT (ours)</b>	<b>48.1</b>



Q: Are there any cups to the left of the tray on top of the table?

A: No

Drew A. Hudson and Christopher D. Manning. GQA: A New Dataset for Real-World Visual Reasoning and Compositional Question Answering. 2019. Available at: <https://arxiv.org/abs/1902.09506>.

# External-Knowledge Based VQA

- Requires querying external knowledge to reason about the image
- Modules added:
  - `llm_query`
- Evaluated on OK-VQA dataset
- Takeaways:
  - Better than zero-shot and on-par with some fine-tuned models
  - Likely due to emphasis on reasoning & CoT

- **Query:** The real live version of this toy does what in the winter?

Generated code

```
def execute_command(image):  
    image = ImagePatch(image)  
    toy = image.simple_query("What is this toy?")  
    result = llm_query("The real live version of  
                        {} does what in the winter?", toy)  
    return result
```

In:



Execution

```
▶ toy = {str} "bear"
```

```
▶ guess = {str} "hibernate"
```

**Result:** "hibernate"

**BLIP-2 result:** "ski"

Table 3. **OK-VQA Results.**

	Accuracy (%) ↑
Sup.	TRiG [13] 50.5
	KAT [16] 54.4
	RA-VQA [32] 54.5
	REVIVE [33] 58.0
	PromptCap [21] 58.8
ZS	PNP-VQA [52] 35.9
	PICa [60] 43.3
	BLIP-2 [30] 45.9
	Flamingo [1] 50.6
	<b>ViperGPT (ours) 51.9</b>

# Video-Based QA

- Requires causal and temporal reasoning about the video
- Modules added for this task:
  - **select\_answer, VideoSegmentation**
- Evaluated on multiple choice NExT-QA dataset
- Takeaways:
  - Achieves SoTA results, surpassing fine-tuned methods
  - Underscores importance of reasoning in video understanding
  - Only has perception for images, but extrapolates to temporal and causal contexts using frames relations

Table 4. **NExT-QA Results.** Our method gets overall state-of-the-art results (including *supervised* models) on the hard split. “T” and “C” stand for “temporal” and “causal” questions, respectively.

		Accuracy (%) ↑		
		Hard Split - T	Hard Split - C	Full Set
Sup.	ATP [7]	45.3	43.3	54.3
	VGT [58]	-	-	56.9
	HiTeA [61]	48.6	47.8	63.1
ZS	<b>ViperGPT (ours)</b>	<b>49.8</b>	<b>56.4</b>	60.0



# Video-Based QA

**Query:** What did the boy do after he dropped the sparkles on the floor?

## Generated code

```
def execute_command(video, question, possible_answers):
    video_segment = VideoSegment(video)
    drop_detected = False
    for i, frame in enumerate(video_segment.frame_iterator()):
        if frame.exists("boy") and frame.exists("sparkles") and \
            frame.simple_query("is the boy dropping the sparkles?") == "yes":
            drop_detected = True
            break
    if drop_detected:
        index_frame = i + 1
    else:
        index_frame = video_segment.num_frames // 2
    frame_of_interest = ImagePatch(video_segment, index_frame)
    boys = frame_of_interest.find("boy")
    if len(boys) == 0:
        boys = [frame_of_interest]
    boy = boys[0]
    caption = boy.simple_query("What is this?")
    info = {
        "Caption of frame after dropping the sparkles": caption,
    }
    answer = select_answer(info, question, possible_answers)
    return answer
```

## Execution

In:



```
frame.exists("boy") and \
frame.exists("sparkles") and \
frame.simple_query("is the boy
dropping the sparkles?") == "yes":
```

▶ frame = {ImagePatch}



▶ i = {int} 25

```
index_frame = i + 1
```

▶ index\_frame = {int} 26

▶ frame\_of\_interest = {ImagePatch}



```
boys = frame_of_interest.find("boy")
```

▶ boy = {ImagePatch}



▶ caption = {str} "a child running  
with fire in his hands"

▶ answer = {str} "pick it up"

**Result:** "Pick it up"

- Loop to identify when the sparkles are dropped
- Identify the image patch of the boy and determine the action he takes
- Use action to select correct answer

# Discussion

# Emergent Capabilities – Real-World Usage

- Beyond benchmarks, Viper-GPT easily adapts to real-world queries
- Simple to add new modules with the provided framework

**Query:** What would the founder of the brand of the car on the left say to the founder of the brand of the car on the right?



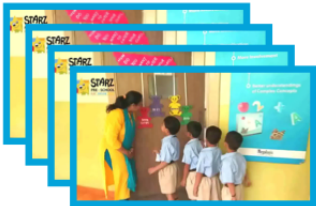
```
def execute_command(image):
    image_patch = ImagePatch(image)
    car_patches = image_patch.find("car")
    car_patches.sort(key=lambda car: car.horizontal_center)
    left_car = car_patches[0]
    right_car = car_patches[-1]
    left_car_brand = left_car.simple_query("What is the brand of this car?")
    right_car_brand = right_car.simple_query("What is the brand of this car?")
    left_car_founder = llm_query(f"Who is the founder of {left_car_brand}?")
    right_car_founder = llm_query(f"Who is the founder of {right_car_brand}?")
    return llm_query(f"What would {left_car_founder} say to {right_car_founder}?")
```



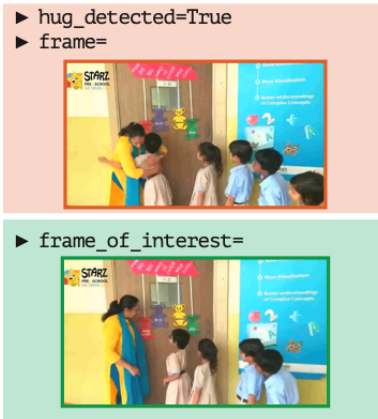
▶ left\_car\_brand='lamborghini'  
▶ right\_car\_brand='ferrari'  
▶ left\_car\_founder='Ferruccio Lamborghini'  
▶ right\_car\_founder='Enzo Ferrari'

**Result:** "Ferruccio Lamborghini might say, 'It's been an honor to be a rival of yours for so many years, Enzo. May our cars continue to push each other to be better and faster!'"

**Query:** Return the two kids that are furthest from the woman right before she hugs the girl



```
def execute_command(video):
    video_segment = VideoSegment(video)
    hug_detected = False
    for i, frame in enumerate(video_segment.frame_iterator()):
        if frame.exists("woman") and frame.exists("girl") and \
            frame.simple_query("Is the woman hugging the girl?") == "yes":
            hug_detected = True
            break
    if hug_detected:
        index_frame = i - 1
        frame_of_interest = ImagePatch(video_segment, index_frame)
        woman_patches = frame_of_interest.find("woman")
        woman_patch = woman_patches[0]
        kid_patches = frame_of_interest.find("kid")
        kid_patches.sort(key=lambda kid: distance(kid, woman_patch))
        kid_patch_1 = kid_patches[-1]
        kid_patch_2 = kid_patches[-2]
        return [kid_patch_1, kid_patch_2]
```



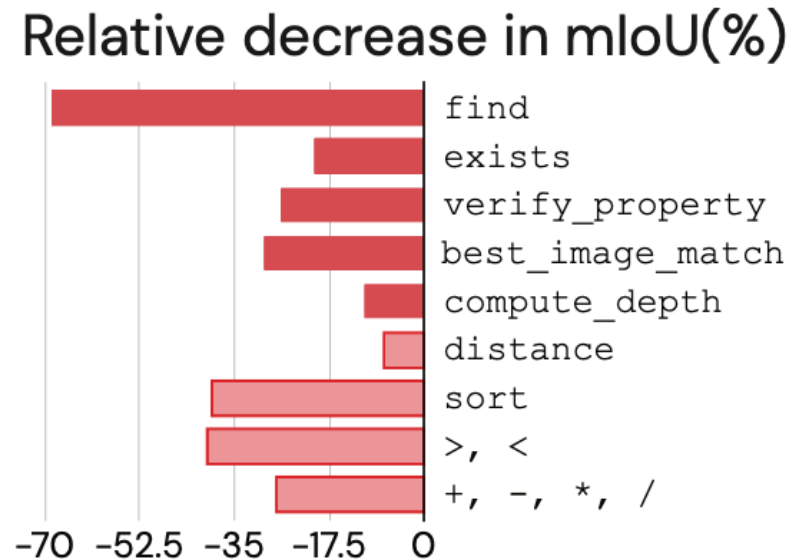
▶ hug\_detected=True  
▶ frame=  
▶ kid\_patches=  
sort(...distance...)  
▶ kid\_patches=

**Result:** [kid\_patch\_1, kid\_patch\_2]

# Emergent Capabilities - Intervention

- New method to evaluate importance of individual modules
  - Cannot evaluate intermediate output --> no ground truth data
  - Cannot compare accuracy between programs --> not all programs use the same modules
- Intervention: Substitute a module with a default value to measure performance drop with nonfunctional module
- Analysis performed on RefCOCO:

Figure 7. **Intervention.** We analyze the importance of various **vision modules** and **Python functions** in the generated programs as measured by the drop in mIoU when they are made nonfunctional.





# Emergent Capabilities – Context-Aware Responses

- Program can be adapted based on context provided as comments
- Important when considering different cultures, norms, and expectations

**Query:** Return the car that is on the correct lane

*# Context: the picture was taken in the US*

```
def execute_command(image):  
    cars = image.find("car")  
    for car in cars:  
        if car.horizontal_center > image.horizontal_center:  
            return car  
    return None
```

*Result: None*



*# Context: the picture was taken in the UK*

```
def execute_command(image):  
    cars = image.find("car")  
    for car in cars:  
        if car.horizontal_center < image.horizontal_center:  
            return car  
    return None
```

*Result:*



# Limitations & Societal Implications

- Limitations:

- Highly dependent on performance of pre-trained models—no ability to fine-tune for specific tasks
- Produced code is interpretable, however not as simple as CoT which is easier for the public to understand
- Programs generated can be overly complex or incorrect for complex tasks—difficult to find error without manual inspection

- Societal Implications

- Enhances interpretability of VLM reasoning process, allowing for intermediate steps to be manually altered
- Framework can be implemented at any scale with any models --> ease of access to more powerful VLM systems
- Inherits biases of pre-trained models it uses (no inherent bias mitigation in the framework)

# Summary of Strengths and Weaknesses

- Strengths:

- Plug-and-Play system: can build modules with any models available
- As better pre-trained models are created (GPT, BLIP, etc.) performance increases
- Outputted programs are interpretable by humans for correction and general understanding
- Achieves strong zero-shot results compared to other zero-shot models

- Weaknesses:

- Performance is generally subpar compared to fine-tuned models
- Not many zero-shot models available for comparison on some tasks (GQA and NExT-QA) and analysis is very shallow
- Heavily dependent on capabilities of pre-trained models—areas that the pre-trained models struggle in will be reflected in the compositional model



# Thank you!