## Topics:

• Vision-Language Models

# **CS 4644-DL / 7643-A ZSOLT KIRA**

Project due April 26th 11:59pm (grace period April 28th)

Fill out CIOS! <a href="https://b.gatech.edu/cios">https://b.gatech.edu/cios</a>

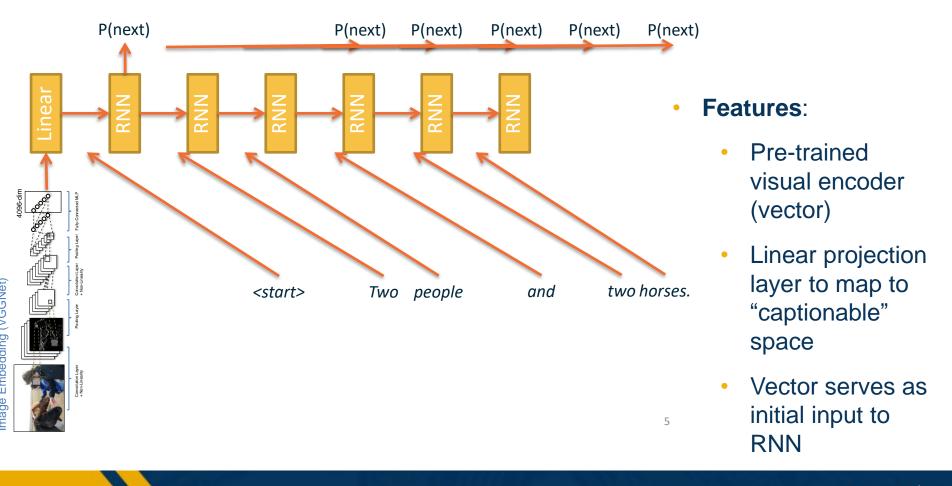


Yang et al., MM-ReAct MM-ReAct: Prompting ChatGPT for Multimodal Reasoning and Action



- Image+LSTM
- CLIP
- Vilbert
- Flamingo
- BLIP/BLIP-2
- LLaVA
- ImageBind / LanguageBind







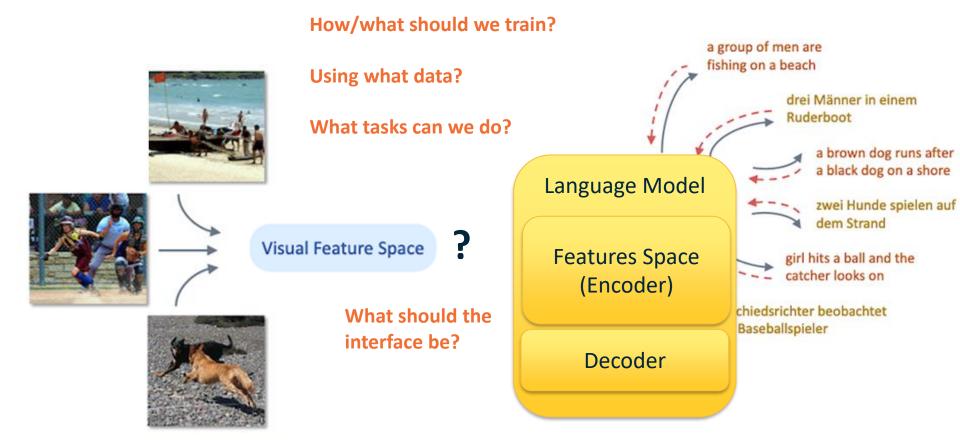






How should we encode this (representations?)?

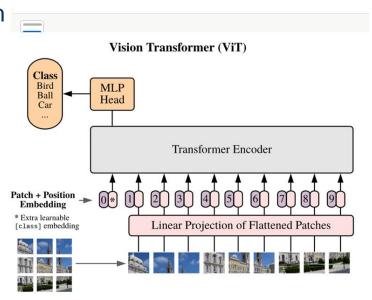
How will they be learned?





#### Potential ways of representing an image?

- Image encoder
  - Any architecture: ResNet, Vision transform (ViT)
  - Randomly initialized, SL/SSL pre-trained

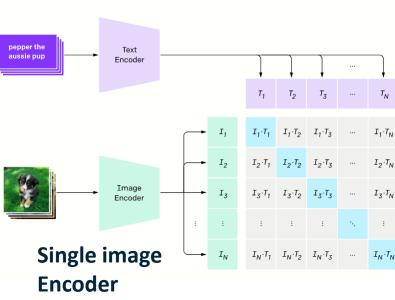


#### Method of alignment: Contrastive Learning

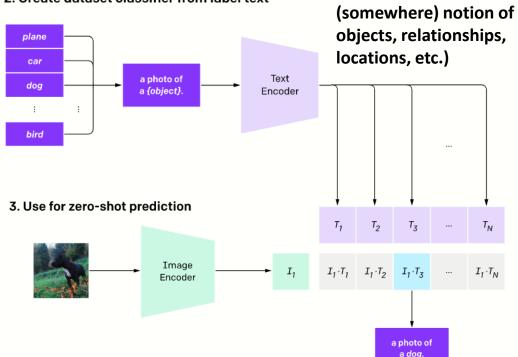
Data: 400M image-text pairs

1. Contrastive pre-training

(ResNet, ViT)



2. Create dataset classifier from label text



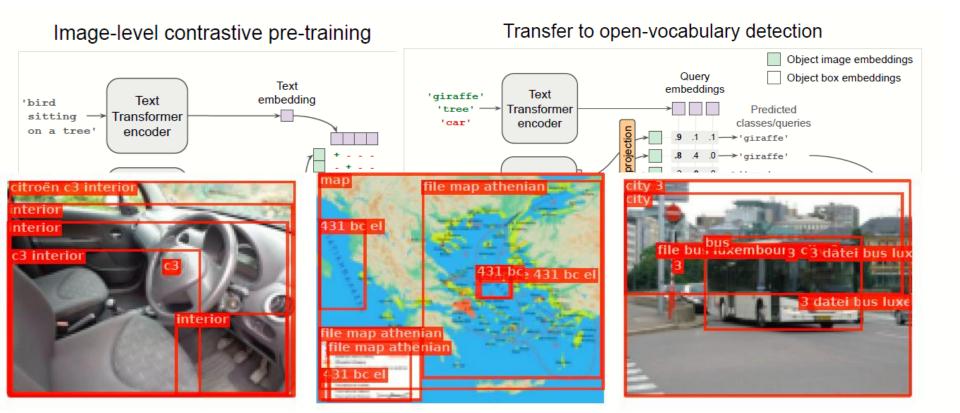
Downside?

Radford et al., Learning Transferable Visual Models From Natural Language Supervision



Coarse-grained.

Has to represent



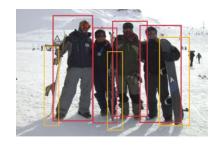
Minderer et al., Simple Open-Vocabulary Object Detection with Vision Transformers Minderer et al., Scaling Open-Vocabulary Object Detection



#### Downside?

#### Potential ways of representing an image?

- Image encoder
  - Randomly initialized, SL/SSL pre-trained
- Alternative:
  - Bounding boxes/segments/regions + features



**Object Detection** 

(List of bounding boxes with class distribution per box)





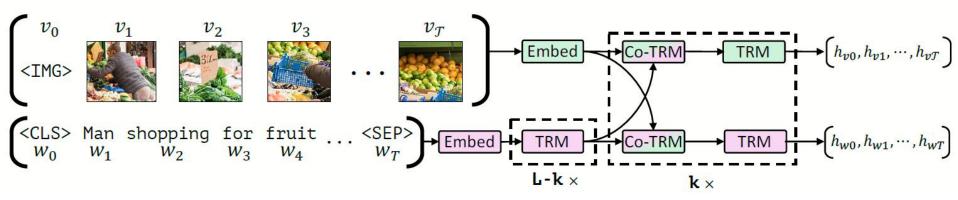




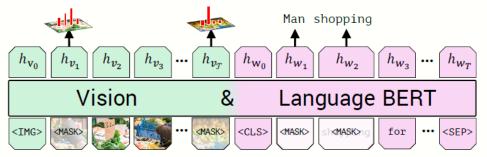


**Instance Segmentation** 



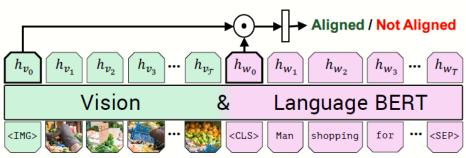


#### **Training: Masked Prediction + Alignment**



(a) Masked multi-modal learning

#### **Interaction/Fusion: Cross-Attention**

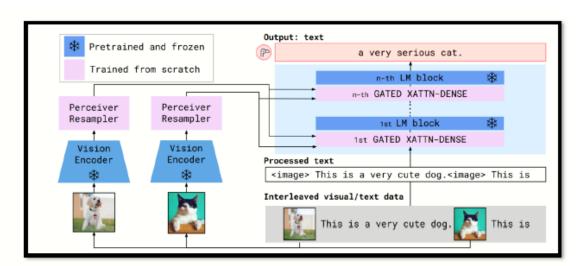


(b) Multi-modal alignment prediction

Lu et al., VilBERT: Pretraining Task-Agnostic Visiolinguistic Representations for Vision-and-Language Tasks



## • Flamingo:



Language Model

Connection Module

Vision Encoder

Pre-trained: 70B Chinchilla

Perceiver Resampler

Gated Cross-attention + Dense

Pre-trained: Nonrmalizer-Free ResNet (NFNet)

## Multimodal Few-Shot Learning with Frozen Language Models

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Serkan Cabi\*

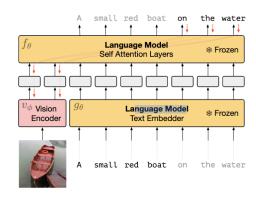
DeepMind cabi@deepmind.com

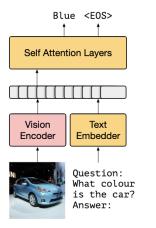
**Felix Hill** 

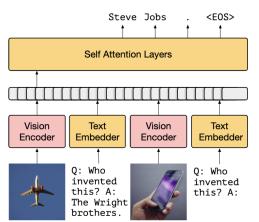
DeepMind felixhill@deepmind.com

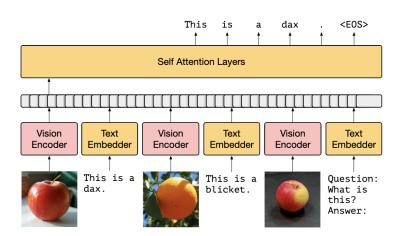
S. M. Ali Eslami
DeepMind
aeslami@deepmind.com

## Training:









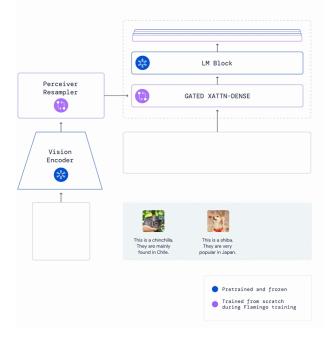
(a) 0-shot VQA

(b) 1-shot outside-knowledge VQA

(c) Few-shot image classification



- What is Flamingo?
  - It's a Visual Language Model (VLM) for Few-Shot Learning that launched by DeepMind.
- Visual Language Model?
  - Processing images to generate reasonable text.
- What can it do?
  - Applicable to image and video understanding tasks via simply prompting it with a few examples
  - captioning, visual dialogue, classification, visual question answering



- Three challenges for training with image/video and text.
  - Supporting both images and videos
    - Images /videos: 2D structure with high dimensionality.
    - Text: 1D sequence
    - Sol.: Introduce <u>Perceiver Resample module</u>.
  - The interaction with image/video and text
    - keep the pretrained model's language understanding and generation capabilities fully intact
    - Sol.: <u>Interleave cross-attention layers with frozen self-attention</u>. <u>gating mechanism</u>.
  - Obtaining multimodal dataset to induce good generalist capabilities
    - Dataset with weak matching problem
    - Sol.: combine dataset with standard strong related paired image/text and video/text datasets

Model structure - Supporting both images and videos

```
Perceiver Resampler
 × num_layers
                                       FFW
                  Attention
             K=V=[X_{\varepsilon},X]
                                          Q=[X]
                                     Learned
                                     latent
                                     queries
                                       fixed #
      Vision
```

```
def perceiver_resampler(
   x_f, # The [T, S, d] visual features (T=time, S=space)
   time_embeddings, # The [T, 1, d] time pos embeddings.
   x, # R learned latents of shape [R, d]
   num_layers, # Number of layers
 """The Perceiver Resampler model."""
 # Add the time position embeddings and flatten.
  x f = x f + time embeddings
  x_f = flatten(x_f) # [T, S, d] -> [T * S, d]
 # Apply the Perceiver Resampler layers.
  for i in range(num_layers):
   # Attention.
   x = x + attention_i(q=x, kv=concat([x_f, x]))
   # Feed forward.
   x = x + ffw_i(x)
 return x
```

pseudo code

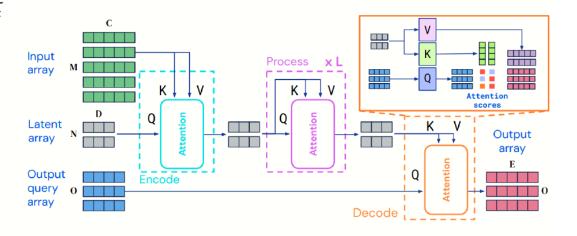
- Using pre-trained ResNet to get visual features X<sub>f</sub>
- Compress the encode image into R tokens
- Core of this module : Attention .
  - Query: the learned latent token X
  - Key=Value: the concatenation of  $X_{f_i}$  and the learned latent token X
  - Better performance by concatenating keys
     and values obtained from latent
- If the input is video
  - X<sub>f</sub> will add time embeddings

Maps a variable size grid of visual features from the Vision

Encoder to a fixed number of output taken (5 in the figure )

## Perceiver / Perceiver IO: Transformer for general data perception

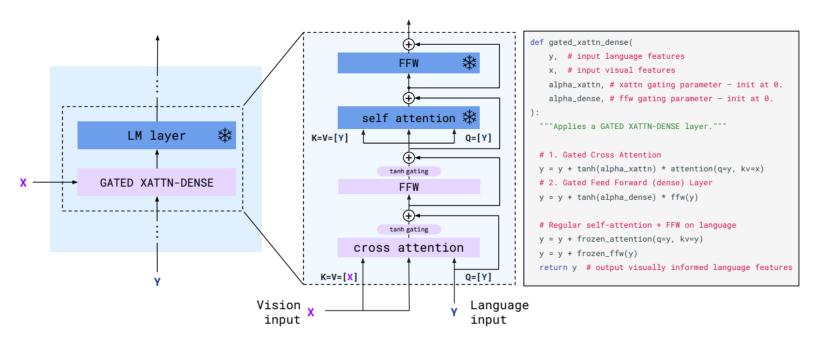
- General data processing method given data can be mapped into sequence of vectors
  - Use cross attention to fetch information from input
  - Self attention to process input.
  - Use cross attention to fetch relevant information and send to output.



Jaegle, Andrew, et al. "Perceiver: General perception with iterative attention." *ICML*, 2021. Jaegle, Andrew, et al. "Perceiver io: A general architecture for structured inputs & outputs." *ICLR*, 2021



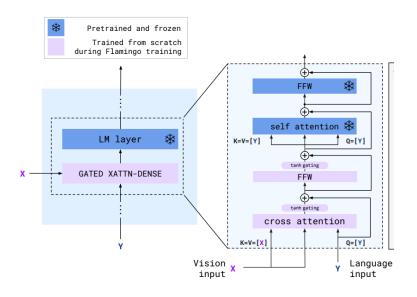
Model structure - The interaction with image/video and text



A Gated Cross attention mechanism is proposed to fuse images and text.



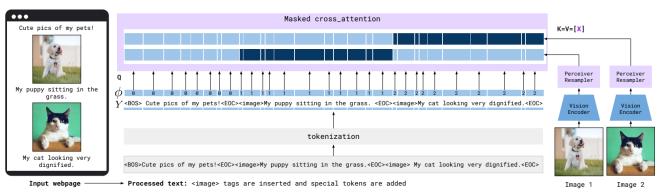
Model structure - The interaction with image/video and text



- Frozen LM layers
  - LM: 70B parameter <u>Chinchilla</u>
  - keep pretrained LM's language understanding
- Gated Cross Attention:
  - Query: Y, Key=Value: X
  - Tanh Gating: Initialized with 0 then gradually increases
  - Transitions from a fully trained text-only model to a visual language model.
- The LM can generate text conditioned on the above visual tokens



Model structure - Interleaved visual data and text support

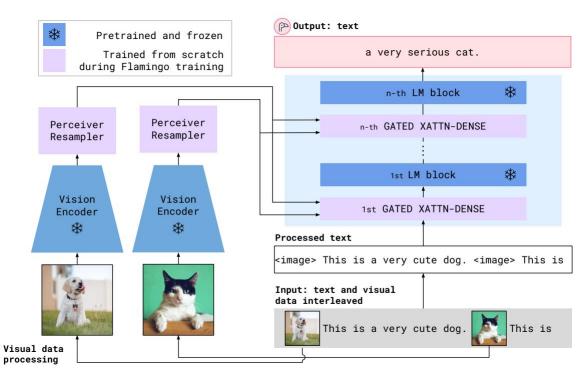


non masked

- Multi-visual input support: per-image/video attention masking
- During Cross-attention,
  - each text can only focus on one image before it.
  - Function  $\phi$ : for each token what is the index of the last preceding image
- During final prediction, each token can focus on all the previously text and image



Overview of the Flamingo Model



 Each image is encoded individually



Model structure - Obtaining multimodal dataset to induce good generalist capabilities



flamingo.



A kid doing a kickflip.

Welcome to my website!

This is a picture of my dog.



This is a picture of my cat.

Image-Text Pairs dataset [N=1, T=1, H, W, C]

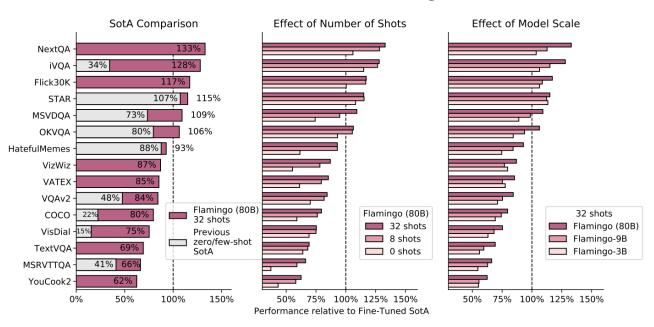
Video-Text Pairs dataset [N=1, T>1, H, W, C]

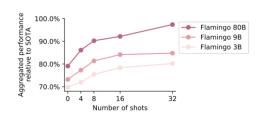
Multi-Modal Massive Web (M3W) dataset [N>1, T=1, H, W, C]

- M3W: Scrapping 43 million webpages from the Internet
- Training on a mixture of vision and language datasets
  - M3W(185M images+ 182G text)
  - ALIGN(1.8B images with alt-text)
  - LTIP (312M images/text)
  - VTP(27M short video/text)



Result: Overview of the results of the Flamingo models



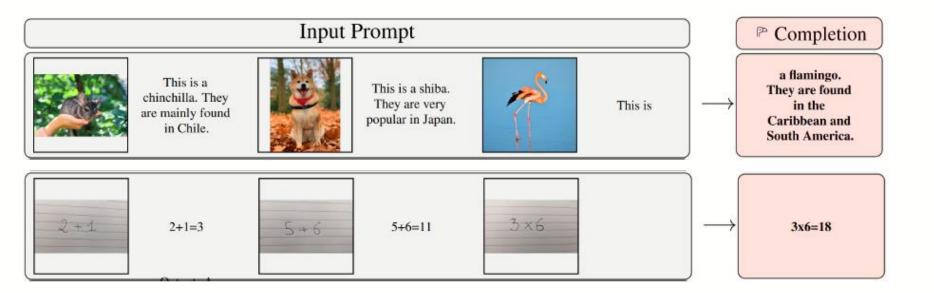


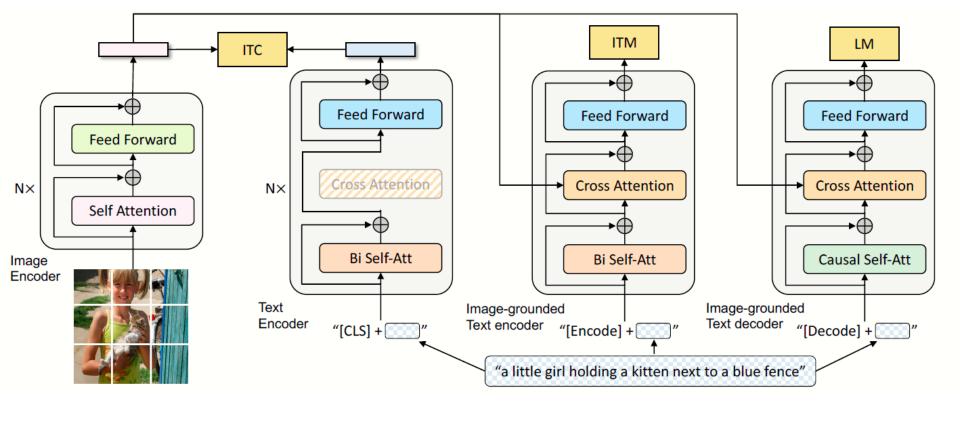
 Larger model sizes and more few-shot examples lead to better performance

 Performance of Flamingo model using different numbers of shots and of different sizes,(without fine-tuned) in comparison with SoTA fine-tuned baseline.

## Flamingo: Multimodal In-Context-Learning



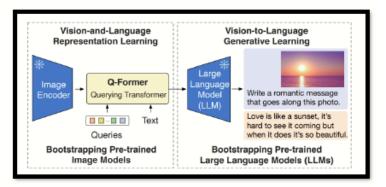




Li et al., BLIP: Bootstrapping Language-Image Pre-training for Unified Vision-Language Understanding and Generation



#### • BLIP2



Language Model

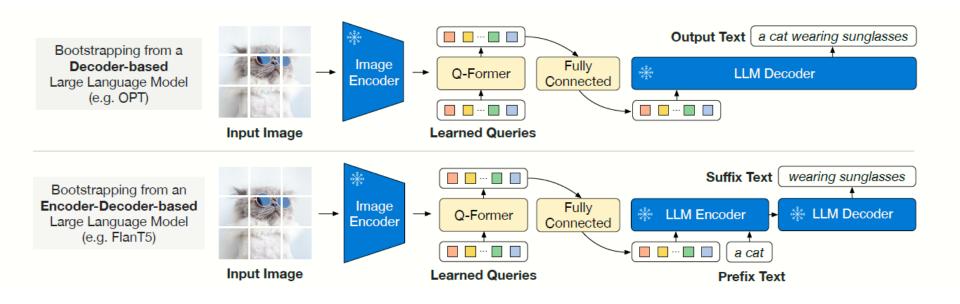
Connection Module

Vision Encoder

Pre-trained: FLAN-T5/OPT

Q-Former: Lightweight
Querying Transformer

Contrastive pre-trained:
EVA/CLIP



Li et al., BLIP-2: Bootstrapping Language-Image Pre-training with Frozen Image Encoders and Large Language Models

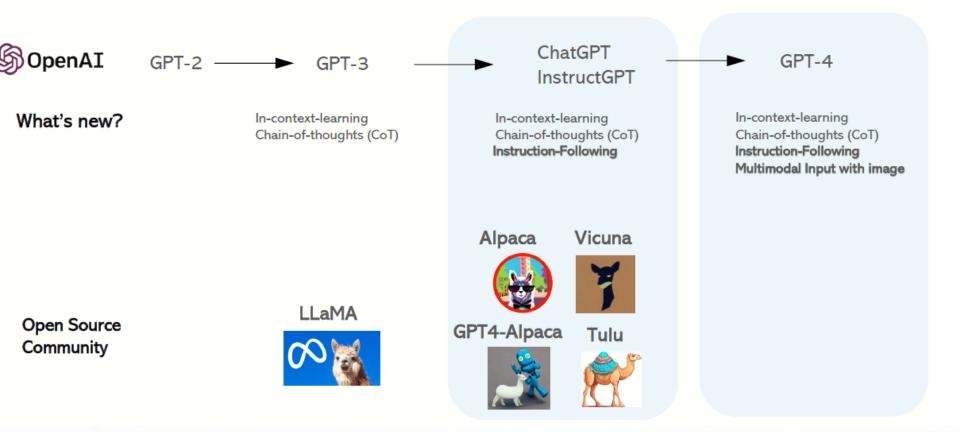
Models	#Trainable Params	#Total Params	V val	QAv2 test-dev	OK-VQA test	GQA test-dev
VL-T5 <sub>no-vqa</sub>	224M	269M	13.5	-	5.8	6.3
FewVLM (Jin et al., 2022)	740M	785M	47.7	-	16.5	29.3
Frozen (Tsimpoukelli et al., 2021)	40M	7.1B	29.6	-	5.9	-
VLKD (Dai et al., 2022)	406M	832M	42.6	44.5	13.3	-
Flamingo3B (Alayrac et al., 2022)	1.4B	3.2B	-	49.2	41.2	-
Flamingo9B (Alayrac et al., 2022)	1.8B	9.3B	-	51.8	44.7	-
Flamingo80B (Alayrac et al., 2022)	10.2B	80B	-	56.3	50.6	-
BLIP-2 ViT-L OPT <sub>2.7B</sub>	104M	3.1B	50.1	49.7	30.2	33.9
BLIP-2 ViT-g OPT <sub>2.7B</sub>	107 <b>M</b>	3.8B	53.5	52.3	31.7	34.6
BLIP-2 ViT-g OPT <sub>6.7B</sub>	108M	7.8B	54.3	52.6	36.4	36.4
BLIP-2 ViT-L FlanT5 <sub>XL</sub>	103M	3.4B	62.6	62.3	39.4	<u>44.4</u>
BLIP-2 ViT-g FlanT5 <sub>XL</sub>	107 <b>M</b>	4.1B	63.1	63.0	40.7	44.2
BLIP-2 ViT-g FlanT5 <sub>XXI</sub>	108 <b>M</b>	12.1B	65.2	65.0	45.9	44.7

Table 2. Comparison with state-of-the-art methods on zero-shot visual question answering.

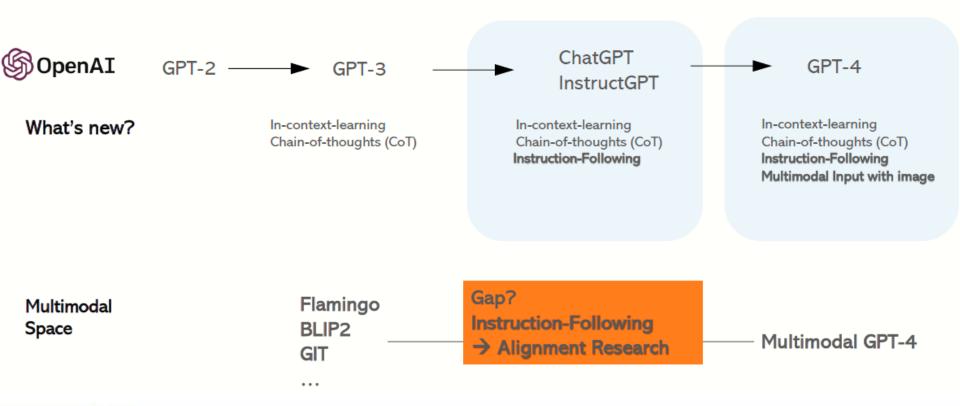
Li et al., BLIP-2: Bootstrapping Language-Image Pre-training with Frozen Image Encoders and Large Language Models



#### Language Modeling: Large Language Models (LLM)



## Recap on Language Modeling: Large Language Models (LLM)



## Instruction Tuning

Input ──► Output

Translation

Hello, Vancouver

你好,温哥华

Summarization

CVPR is the premier annual computer vision event comprising the main conference and several co-located workshops and short courses. This year, CVPR will be single track such that everyone (with full passport registration) can attend everything.

CVPR: top computer vision event, single-track, accessible to all.

- · Task instructions are implicit.
- Individual models are trained, or multi-tasking without specifying the instructions
- Hard to generalize to new tasks in zero-shot

## Instruction Tuning

Instruction

Input ──► Output

Translate English into Simplified Chinese

Hello, Vancouver

你好,温哥华

Summarize in just 10 words to make the message even more brief and easier to remember.

CVPR is the premier annual computer vision event comprising the main conference and several co-located workshops and short courses. This year, CVPR will be single track such that everyone (with full passport registration) can attend everything.

CVPR: top computer vision event, single-track, accessible to all.

- Task instructions are explicit, expressed in natural language
- · One single model is trained, multi-tasking with specified instructions
- Natural and easy to generalize to new tasks in zero-shot



How to collect a diverse set of high-quality instructions and their responses?

- ☐ Human-Human: Collected from humans with high cost
- ☐ Human-Machine: A Strong LLM Teacher such as GPT3 and GPT4

translation example summarization example

Please generate new instructions that meet the requirements: ....

Seed Examples In-Context Learning New Machine-Generated Examples

## **Instruction Tuning with Open-Source LLMs**

## Self-Instruct with Strong Teacher LLMs & Mixed Human Data

	LLaMA	Alpaca	Vicuna	GPT4-Alpaca	•••	Tulu
Data Source		GPT-3.5	ShareGPT (Human & GPT)	GPT-4 (text-only)		Mixed Data
Instruction- following Data (#Turns)	None	52K	500K (~150K conversions)	52K	•••	

# Visual Instruction Tuning with GPT-4

https://llava-vl.github.io/

Haotian Liu\*, Chunyuan Li\*, Qingyang Wu, Yong Jae Lee (\* Equal contribution)

## Self-Instruct with Strong Teacher LLMs

### But No Teacher is available on multiGPT4?







Teacher

GPT-3.5 ShareGPT (Human & GPT

Instructionfollowing Data

None

52K

700K (70 conversions)

SPT-4-IIM



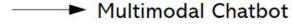
GPT-4 (text-only)

LLaVA



GPT-4 (text-only)

 158K multimodal instruction following data (First & High Quality)



Large Language and Vision Assistant

# GPT-assisted Visual Instruction Data Generation

- Rich Symbolic Representations of Images
- In-context-learning with a few manual examples

→ Text-only GPT-4

#### Context type 1: Captions

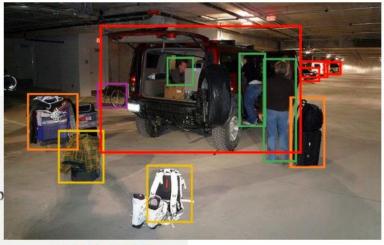
A group of people standing outside of a black vehicle with various luggage. Luggage surrounds a vehicle in an underground parking area

People try to fit all of their luggage in an SUV.

The sport utility vehicle is parked in the public garage, being packed for a trip Some people with luggage near a van that is transporting it.

#### Context type 2: Boxes

person: [0.681, 0.242, 0.774, 0.694], person: [0.63, 0.222, 0.686, 0.516], person: [0.444, 0.233, 0.487, 0.34], backpack: [0.384, 0.696, 0.485, 0.914], backpack: [0.755, 0.413, 0.846, 0.692], suitcase: [0.758, 0.413, 0.845, 0.69], suitcase: [0.1, 0.497, 0.173, 0.579], bicycle: [0.282, 0.363, 0.327, 0.442], car: [0.786, 0.25, 0.848, 0.322], car: [0.783, 0.27, 0.827, 0.335], car: [0.86, 0.254, 0.891, 0.3], car: [0.261, 0.101, 0.787, 0.626]



### GPT-assisted Visual Instruction Data Generation

## Three type of instruction-following responses

messages = [ {"role":"system", "content": f"""You are an AI visual assistant, and you are seeing a single image. What you see are provided with five sentences, describing the same image you are looking at. Answer all questions as you are seeing the image.

Design a conversation between you and a person asking about this photo. The answers should be in a tone that a visual AI assistant is seeing the image and answering the question. Ask diverse questions and give corresponding answers.

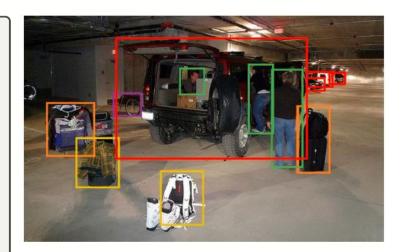
Include questions asking about the visual content of the image, including the object types, counting the objects, object actions, object locations, relative positions between objects, etc. Only include questions that have definite answers:

- (1) one can see the content in the image that the question asks about and can answer confidently;
- (2) one can determine confidently from the image that it is not in the image. Do not ask any question that cannot be answered confidently.

Also include complex questions that are relevant to the content in the image, for example, asking about background knowledge of the objects in the image, asking to discuss about events happening in the image, etc. Again, do not ask about uncertain details. Provide detailed answers when answering complex questions. For example, give detailed examples or reasoning steps to make the content more convincing and well-organized. You can include multiple paragraphs if necessary."""}

```
for sample in fewshot_samples:
    messages.append({"role":"user", "content":sample['context']})
    messages.append({"role":"assistant", "content":sample['response']})
messages.append({"role":"user", "content":'\n'.join(query)})
```

the passengers uncomfortable during the trip.



### GPT-assisted Visual Instruction Data Generation

messages = [ {"role": "system", "content": f"""You are an AI visual assistant, and you are seeing a single image. What you see are provided with five sentences, describing the same image you are looking at. Answer all questions as you are seeing the image.

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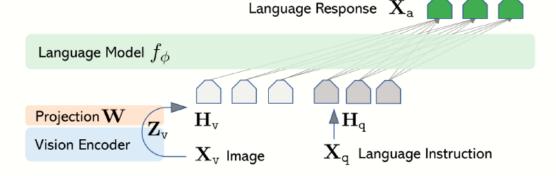
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messages.append({"role":"user", "content":'\n'.join(query)})
```



# LLaVA: Large Language-and-Vision Assistant

□ Architecture



# ☐ Two-stage Training

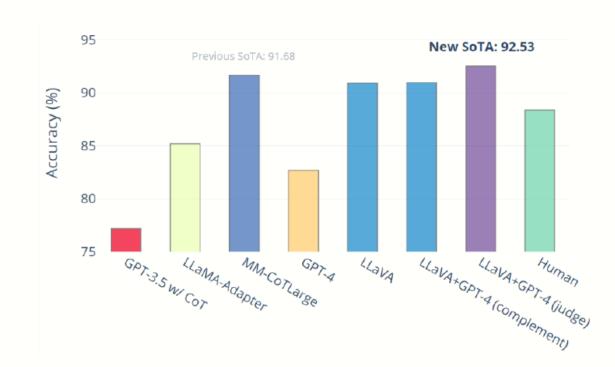
•Stage 1: Pre-training for Feature Alignment.

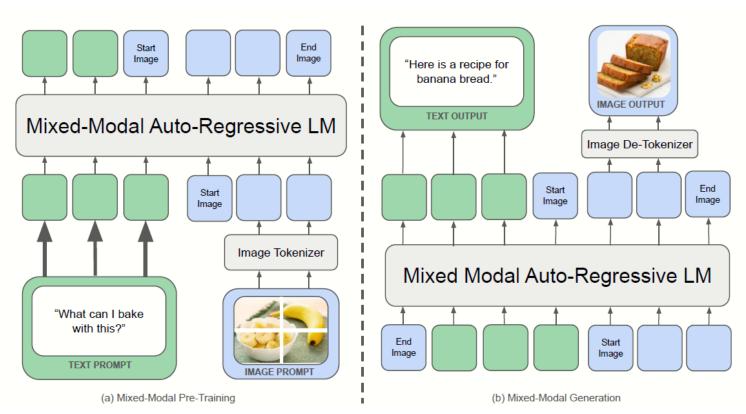
Only the projection matrix is updated, based on a subset of CC3M.

- •Stage 2: Fine-tuning End-to-End. Both the projection matrix and LLM are updated
  - •Visual Chat: Our generated multimodal instruction data for daily user-oriented applications.
  - •Science QA: Multimodal reasoning dataset for the science domain.

# Science QA: New SoTA with the synergy of LLaVA with GPT-4

- LLaVA alones achieve 90.92%
- We use the text-only GPT-4 as the juedge, to predict the final answer based on its own previous answers and the LLaVA answers.
- This ``GPT-4 as juedge" scheme yields a new SOTA 92.53%
- GPT-4 is an effective model ensemble method

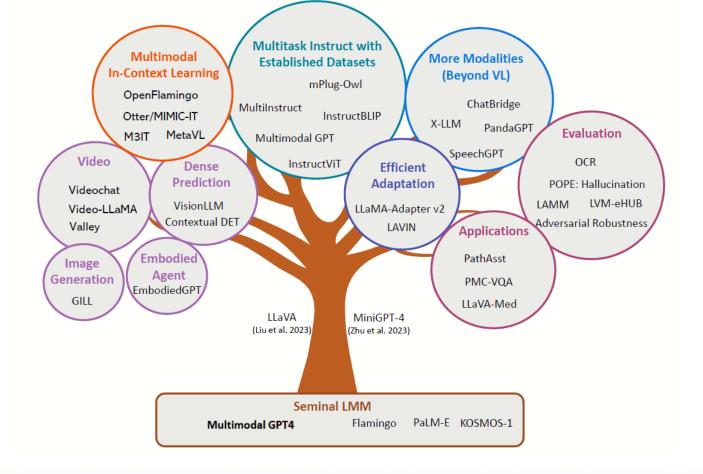


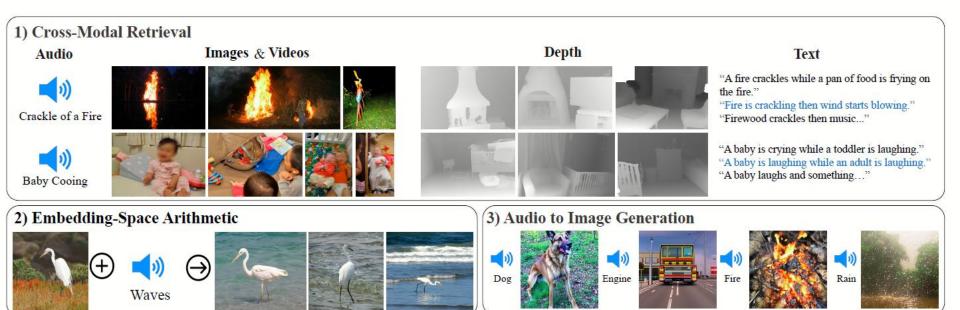


Unifying image models, generation (diffusion models?), and autoregressive models still an open problem!

Meta, Chameleon: Mixed-Modal Early-Fusion Foundation Models

Datasets	Previous Open-source SoTA	Claude-3.5 Sonnet-0620		InternVL2.5 78B	Qwen2-VL 72B	Qwen2.5-VL 72B	Qwen2.5-VL 7B	Qwen2.5-VL 3B
College-level Problems								
MMMU <sub>val</sub> (Yue et al., 2023)	70.1 Chen et al. (2024d)	68.3	69.1	70.1	64.5	70.2	58.6	53.1
MMMU-Pro <sub>overall</sub> (Yue et al., 2024)	48.6 Chen et al. (2024d)	51.5	51.9	48.6	46.2	51.1	38.3	31.56
Math								
MathVista <sub>mini</sub> (Lu et al., 2024)	72.3 Chen et al. (2024d)	67.7	63.8	72.3	70.5	74.8	68.2	62.3
MATH-Vision <sub>full</sub> (Wang et al., 2024d)	32.2 Chen et al. (2024d)	-	30.4	32.2	25.9	38.1	25.1	21.2
MathVerse <sub>mini</sub> (Zhang et al., 2024c)	51.7 Chen et al. (2024d)	-	50.2	51.7	-	57.6	49.2	47.6
General Visual Question Answering								
MegaBench (Chen et al., 2024b)	47.4 MiniMax et al. (2025)	52.1	54.2	45.6	46.8	51.3	36.8	28.9
MMBench-EN <sub>test</sub> (Liu et al., 2023d)	88.3 Chen et al. (2024d)	82.6	83.4	88.3	86.9	88.6	83.5	79.1
MMBench-CN <sub>test</sub> (Liu et al., 2023d)	88.5 Chen et al. (2024d)	83.5	82.1	88.5	86.7	87.9	83.4	78.1
MMBench-V1.1-EN <sub>test</sub> (Liu et al., 2023d)	87.4 Chen et al. (2024d)	80.9	83.1	87.4	86.1	88.4	82.6	77.4
MMStar (Chen et al., 2024c)	69.5 Chen et al. (2024d)	65.1	64.7	69.5	68.3	70.8	63.9	55.9
MME <sub>sum</sub> (Fu et al., 2023)	2494 Chen et al. (2024d)	1920	2328	2494	2483	2448	2347	2157
MuirBench (Wang et al., 2024a)	63.5 Chen et al. (2024d)	-	68.0	63.5	-	70.7	59.6	47.7
BLINK <sub>val</sub> (Fu et al., 2024c)	63.8 Chen et al. (2024d)	-	68.0	63.8	-	64.4	56.4	47.6
CRPE <sub>relation</sub> (Wang et al., 2024h)	78.8 Chen et al. (2024d)	-	76.6	78.8	-	79.2	76.4	73.6
HallBench <sub>avg</sub> (Guan et al., 2023)	58.1 Wang et al. (2024f)	55.5	55.0	57.4	58.1	55.2	52.9	46.3
MTVQA (Tang et al., 2024)	31.9 Chen et al. (2024d)	25.7	27.8	31.9	30.9	31.7	29.2	24.8
RealWorldQA <sub>avg</sub> (X.AI, 2024)	78.7 Chen et al. (2024d)	60.1	75.4	78.7	77.8	75.7	68.5	65.4
MME-RealWorlden (Zhang et al., 2024f)	62.9 Chen et al. (2024d)	51.6	45.2	62.9	-	63.2	57.4	53.1
MMVet <sub>turbo</sub> (Yu et al., 2024)	74.0 Wang et al. (2024f)	70.1	69.1	72.3	74.0	76.2	67.1	61.8
MM-MT-Bench (Agrawal et al., 2024)	7.4 Agrawal et al. (2024)	7.5	7.72	-	6.59	7.6	6.3	5.7





Girdhar et al., ImageBind: One Embedding Space To Bind Them All

### More Modalities (Beyond VL)

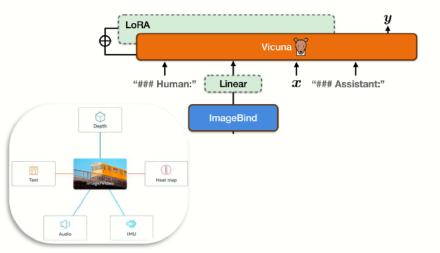
- · ChatBridge: Bridging Modalities with Large Language Model as a Language Catalyst
- PandaGPT: One Model To Instruction-Follow Them All
- · SpeechGPT: Empowering large language models with intrinsic cross-modal conversational abilities
- X-LLM: Bootstrapping Advanced Large Language Models by Treating Multi-Modalities as Foreign Languages

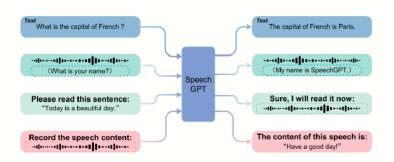
More Modalities (Beyond VL)

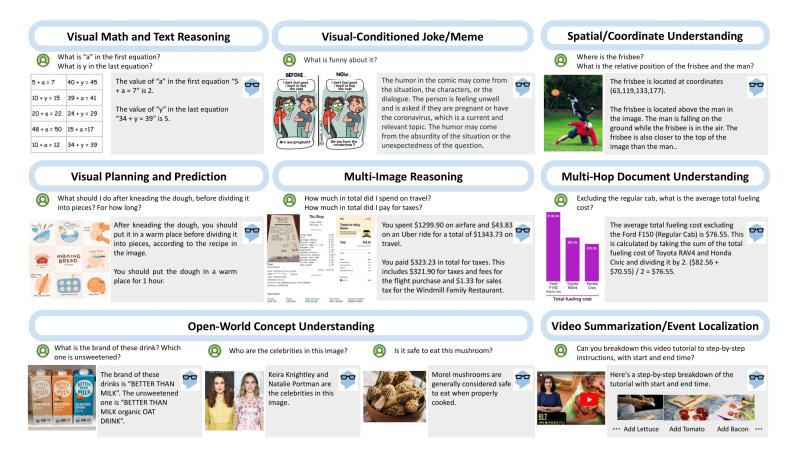
ChatBridge

X-LLM PandaGPT

SpeechGPT







Yang et al., MM-ReAct MM-ReAct: Prompting ChatGPT for Multimodal Reasoning and Action



- Vision+Language (and multi-modal) are hot!
- Why?
  - Align various interface modalities
  - Leverage more data (all modalities)
  - Physical world inherently multi-modal

- Large number of design choices!
  - Vision encoding?
  - Method of alignment?
  - Method of fusion?
  - Grounding?

- Tasks:
  - Image ⇔ language
  - Visual question answering
    - + Interaction
  - Embodied AI

#### **Resources:**

https://www.youtube.com/@VLPTutorial